

Disordered systems for neurocomputation

Arthur Montanari



Center for
Network Dynamics

Department of Physics and Astronomy

Northwestern University

May 19, 2026

Disordered systems for **stability** & **neurocomputation**

Arthur Montanari



Center for
Network Dynamics

Department of Physics and Astronomy

Northwestern University

May 19, 2026

A short story on power grid stability



POWER BLACKOUT: SPAIN DECLARES STATE OF EMERGENCY

BBC


Home News Sport Business Technology Health Culture Arts Travel Earth Audio Video Live Documentaries

'Multiple factors' caused 2025 Spain and Portugal blackout, says report

20 March 2026

Guy Hedgecoe
Madrid

Share Save Add as preferred on Google



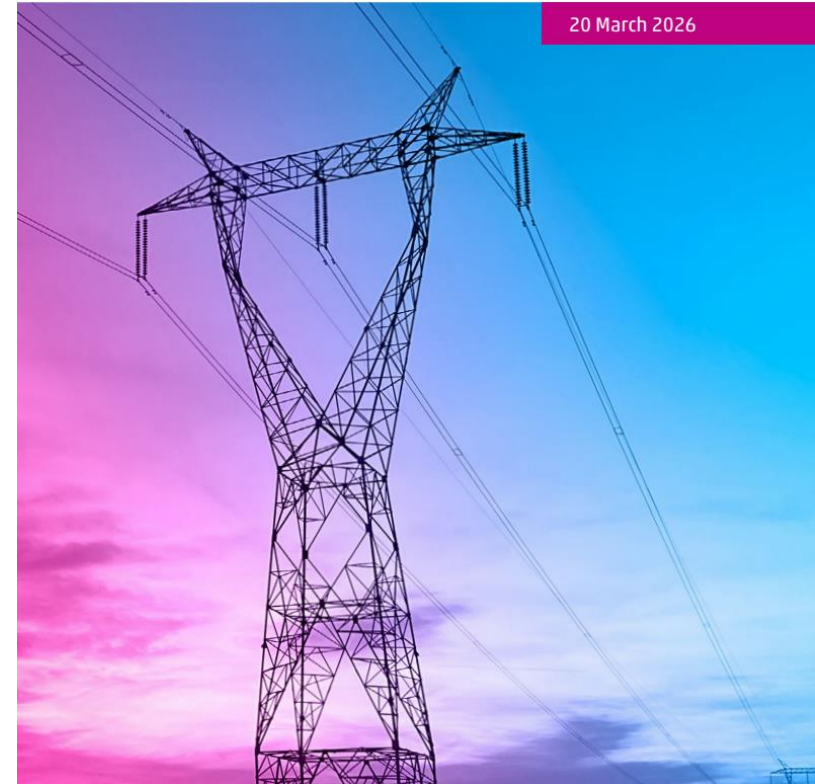
The blackout caused chaos at transport hubs like Barcelona Sants railway station

» Grid Incident in Spain and Portugal on 28 April 2025

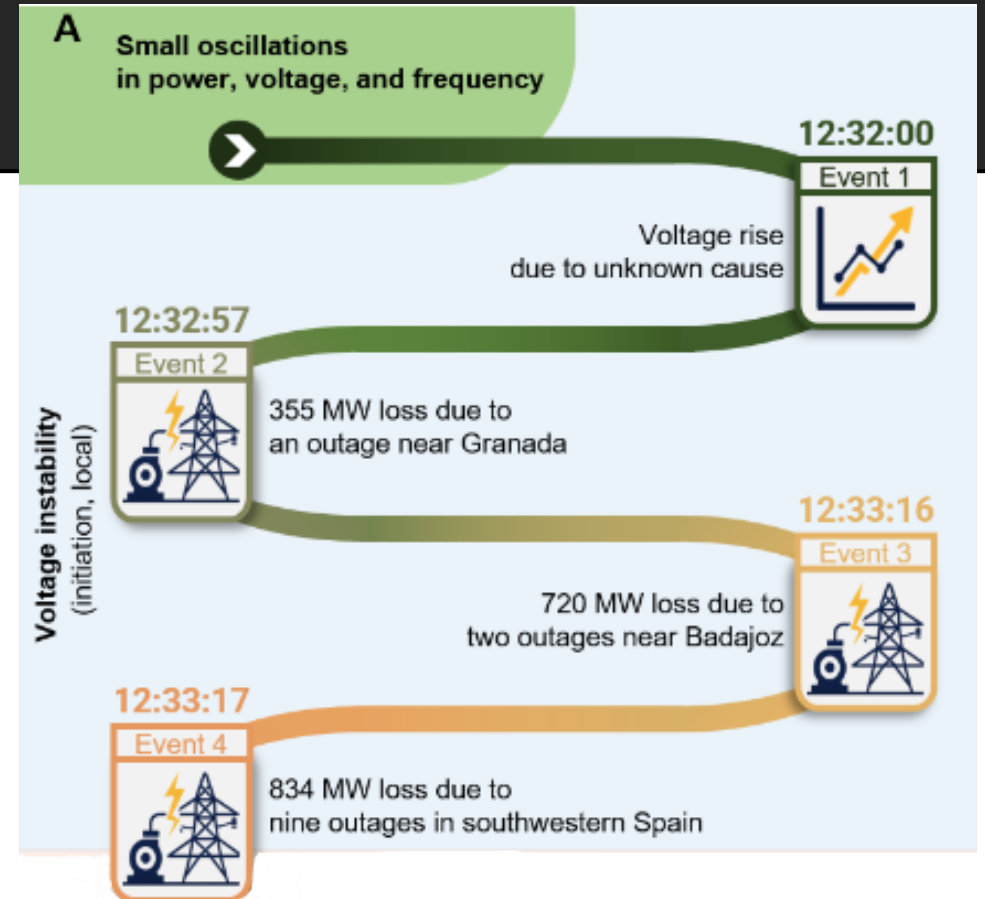
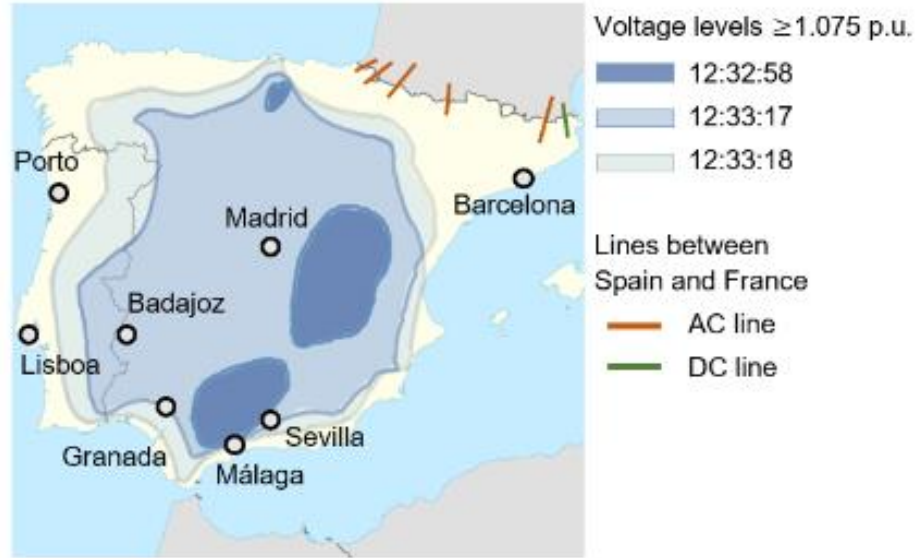
ICS Investigation Expert Panel
Final Report



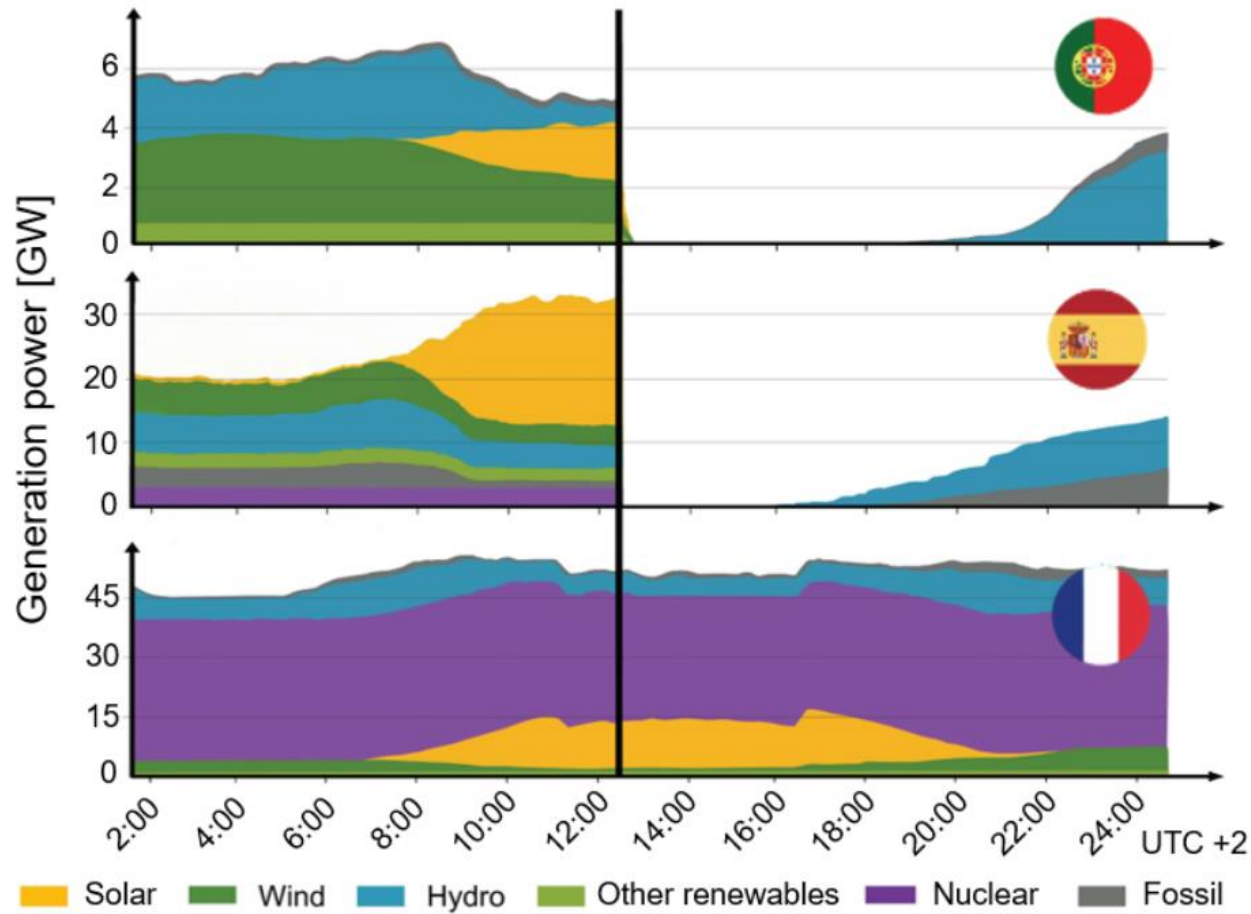
20 March 2026



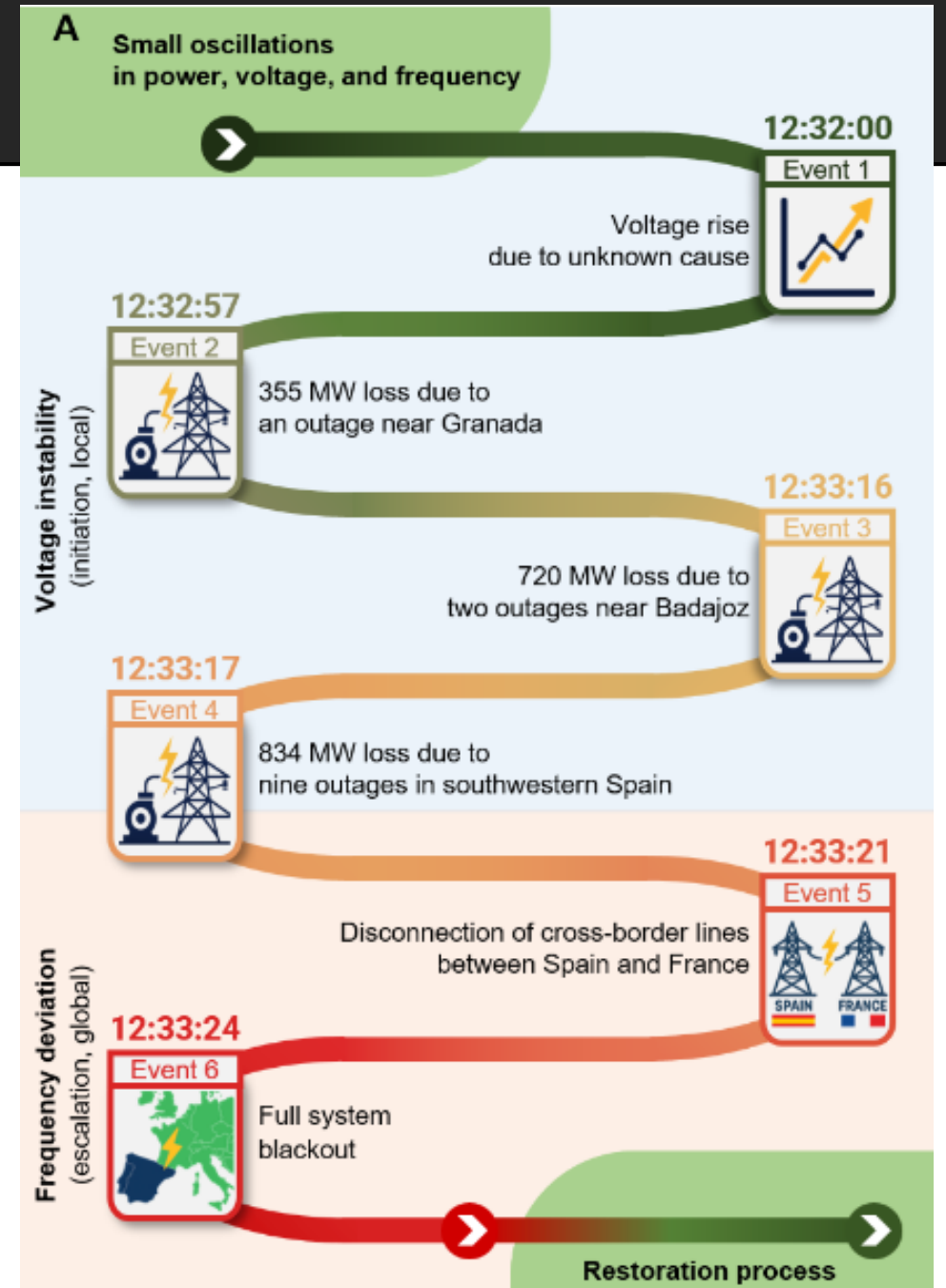
The Iberian blackout



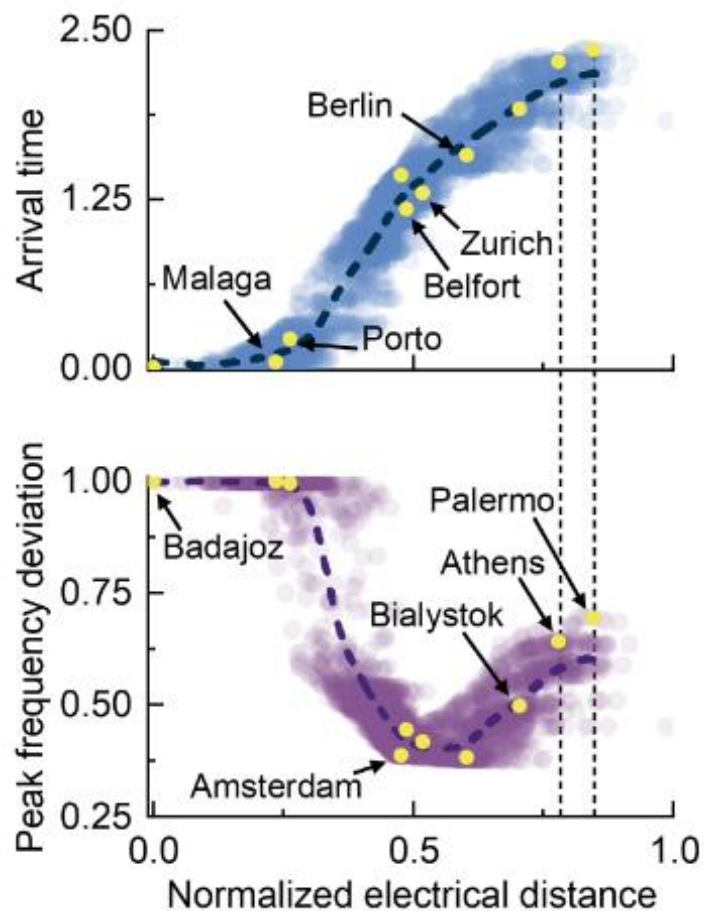
The Iberian blackout



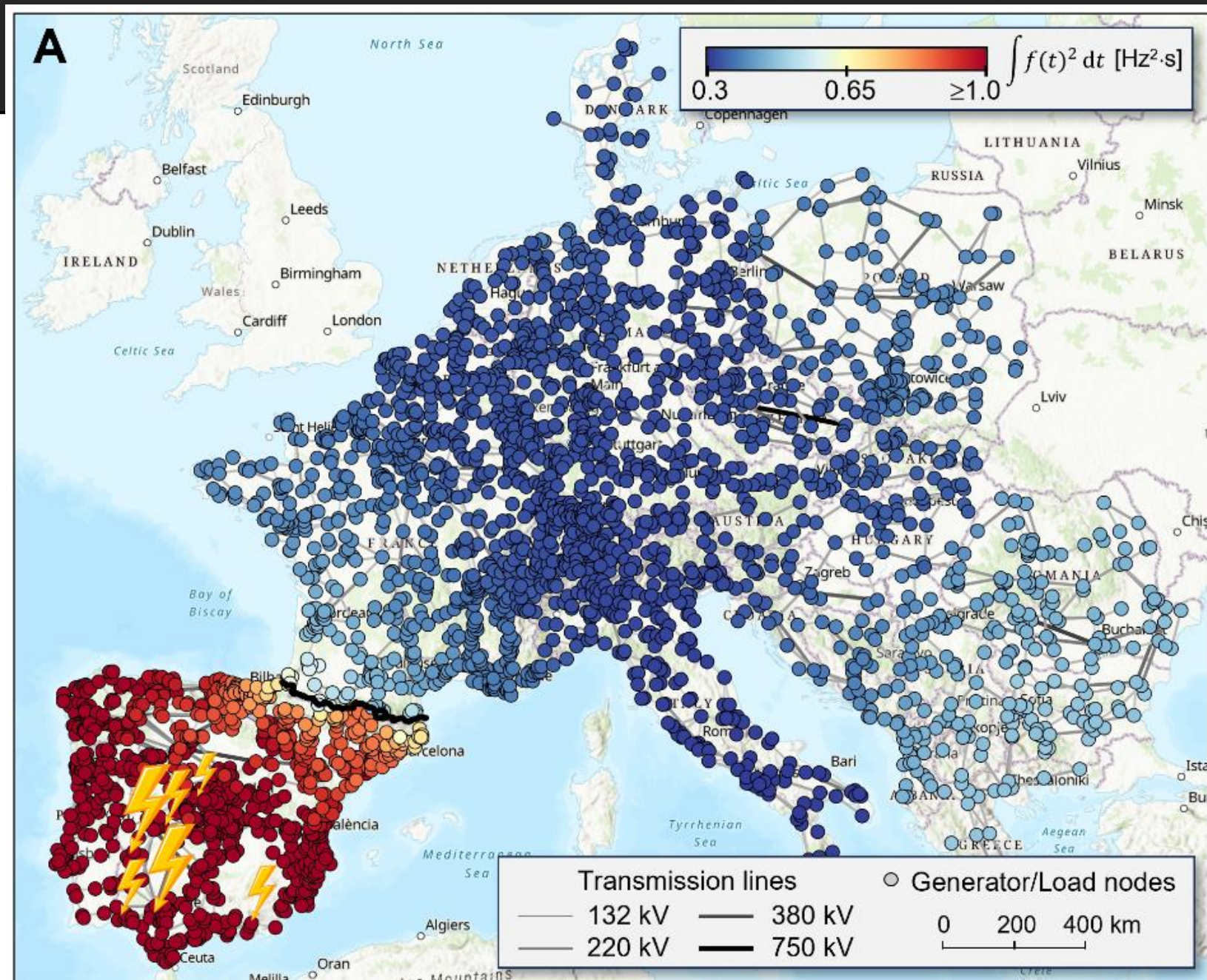
Wang, ANM, Motter.
Joule, accepted (2026).



Simulations



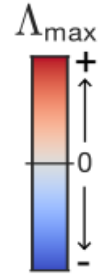
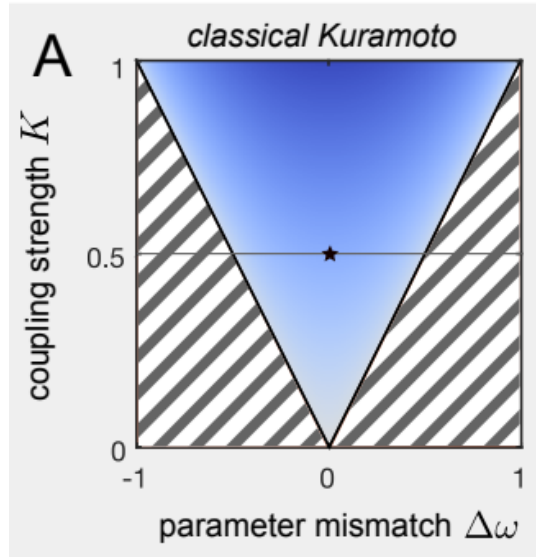
Wang, ANM, Motter.
Joule, accepted (2026).



Part I: Disorder & Stability

Part II: Disorder & Computation

Complex systems perspective



$$\dot{\phi}_i = \omega_i + K \sum_{j=1}^N A_{ij} \sin(\phi_j - \phi_i)$$

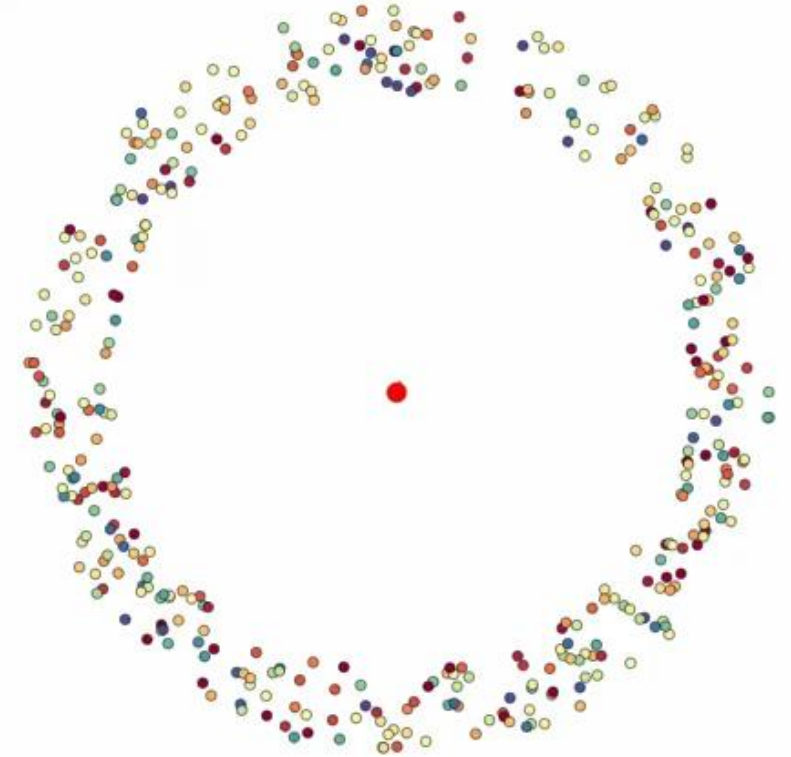
$$N = 2 \rightarrow \left| \frac{\Delta\omega}{2K} \right| < 1$$

$N > 2$, Strogatz. *Physica D* (2000).

Rodrigues, et al.
Physics Reports (2016).

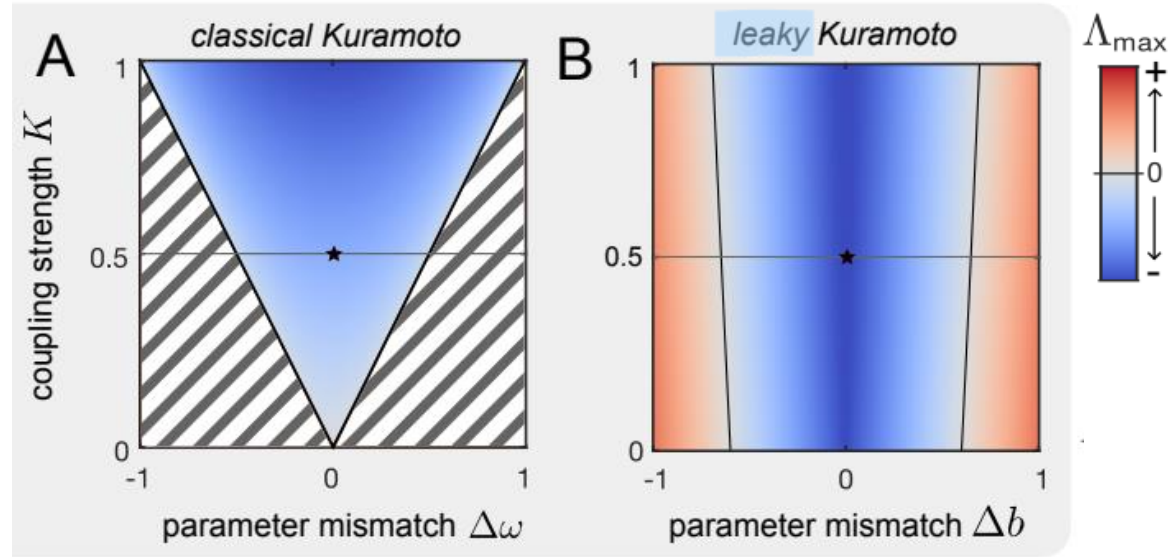
Dorfler, Chertkov, Bullo.
PNAS (2013).

$$\|L^\dagger \omega\|_{\mathcal{E}, \infty} < 1$$



[www.complexity-explorables.org/
slides/ride-my-kuramotocycle/](http://www.complexity-explorables.org/slides/ride-my-kuramotocycle/)

Complex systems perspective



Leaky Kuramoto
(synchronization)

$$\dot{\phi}_i + b_i \phi_i = \omega + \sum_j A_{ij} \sin(\phi_j - \phi_i) \quad -(B + L)$$

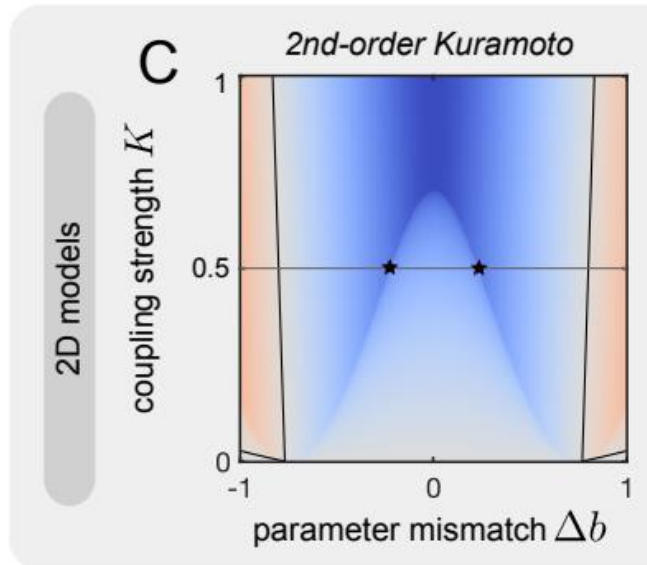
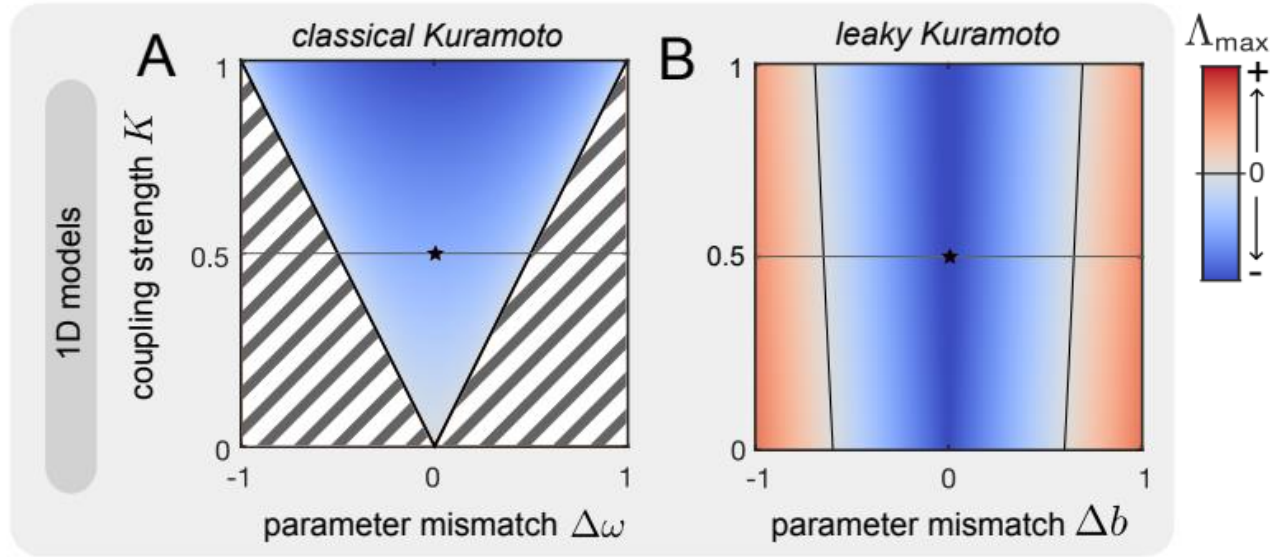
Driven Kuramoto
(pacemaker)

$$\dot{\phi}_i + b_i \sin(\phi_i - \psi) = \omega + \sum_j A_{ij} \sin(\phi_j - \phi_i) \quad -(B + L)$$

Consensus
(opinion, coordination)

$$\dot{x}_i + b_i x_i = \sum_j A_{ij} (x_j - x_i) \quad -(B + L)$$

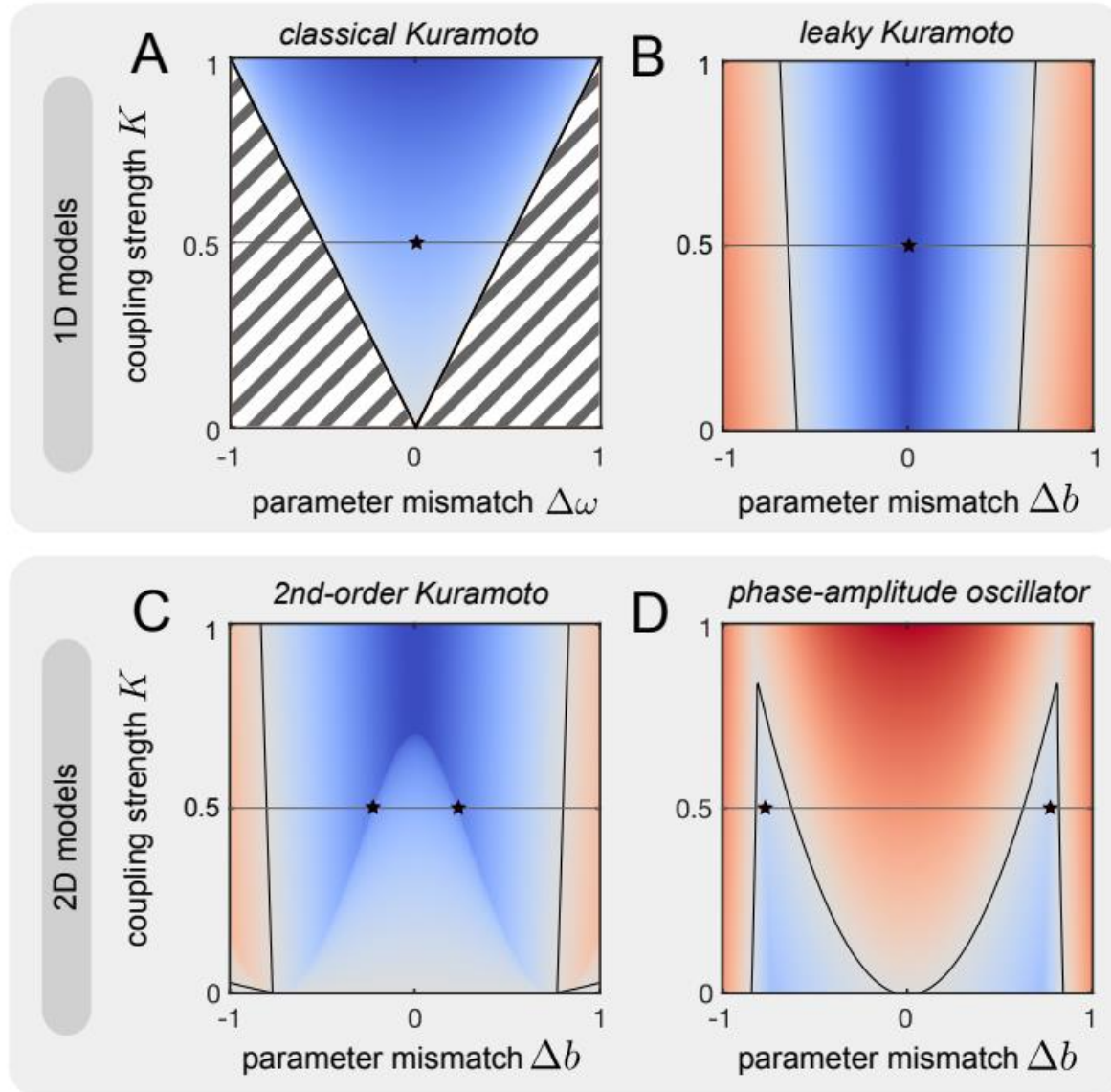
Disorder-promoted stability



2nd-order Kuramoto
(power grids)

$$\ddot{\phi}_i + b_i \dot{\phi}_i = P + \sum_j A_{ij} \sin(\phi_j - \phi_i)$$

Disorder-promoted stability

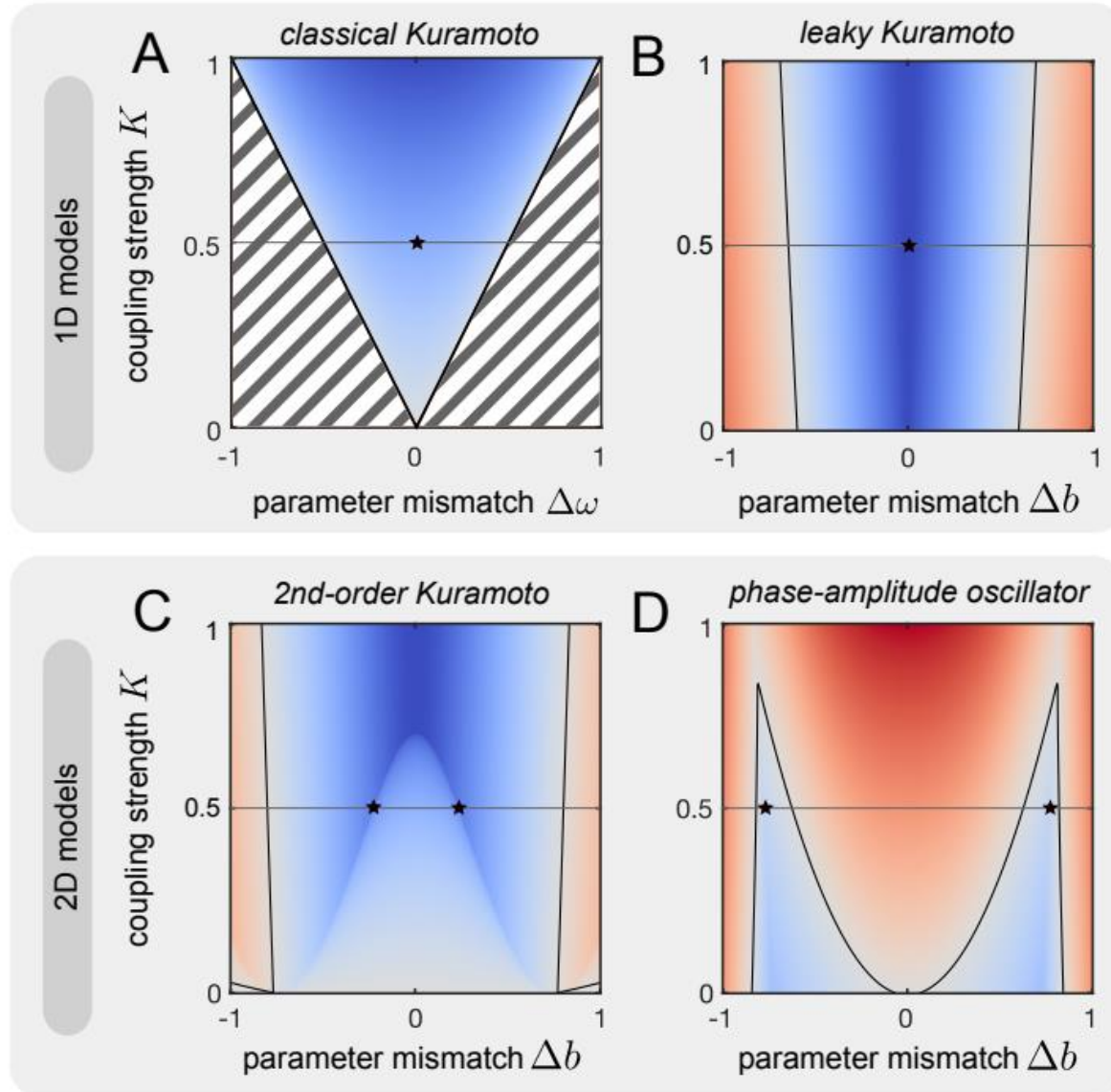


Phase-amplitude oscillator

$$\dot{r}_i = b_i r_i (1 - r_i) + \varepsilon r_i \sum_j A_{ij} \cos(\phi_j - \phi_i)$$

$$\dot{\phi}_i = \omega + r_i - 1 + r_i \sum_j A_{ij} \sin(\phi_j - \phi_i)$$

Disorder-promoted stability: condition?



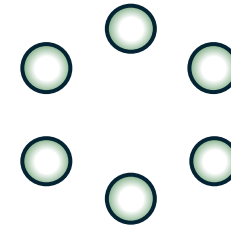
$$\dot{\mathbf{x}}_i = \mathbf{f}(\mathbf{x}_i; b_i) + \sum_{j=1}^N A_{ij} \mathbf{g}(\mathbf{x}_i, \mathbf{x}_j)$$

Given a network structure,
what is the optimal
parameter assignment
that maximizes stability?

Disorder-promoted stability: condition?

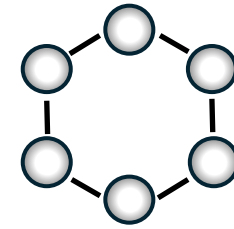
$$\dot{\mathbf{x}}_i = \mathbf{f}(\mathbf{x}_i; b_i) + \sum_{j=1}^N A_{ij} \mathbf{g}(\mathbf{x}_i, \mathbf{x}_j)$$

nodal
symmetries



$$P\mathbf{b} = \mathbf{b}$$

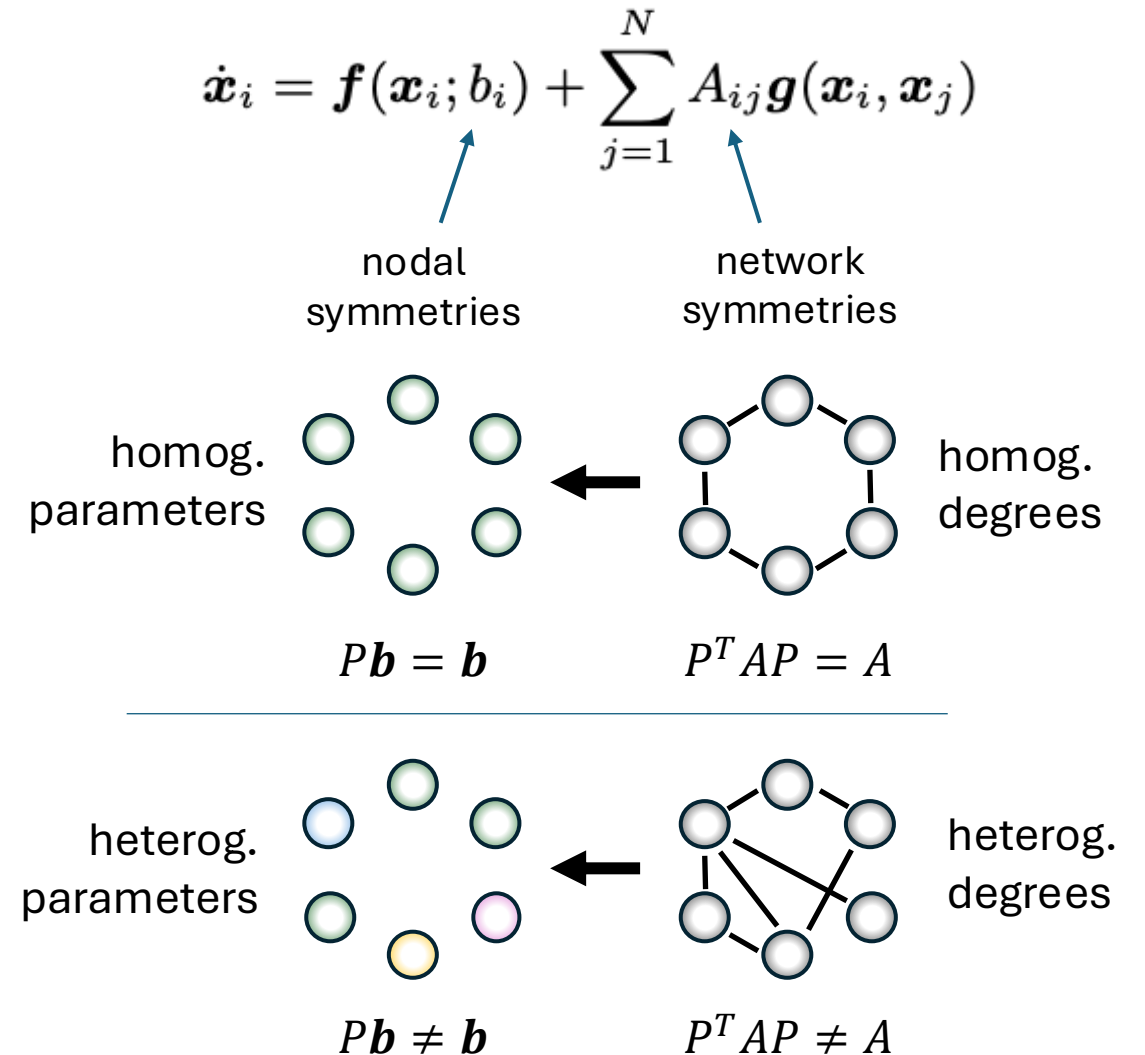
network
symmetries



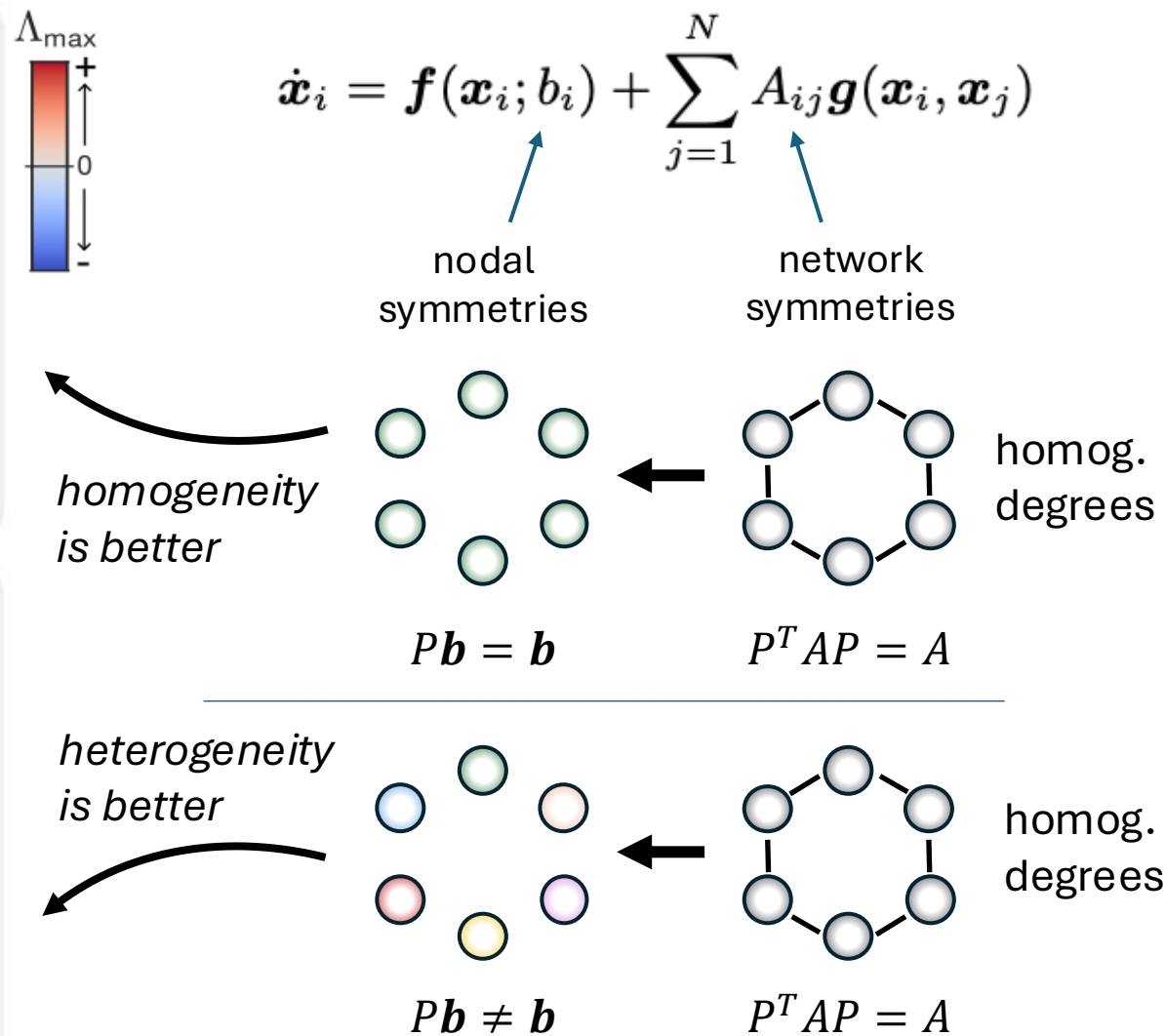
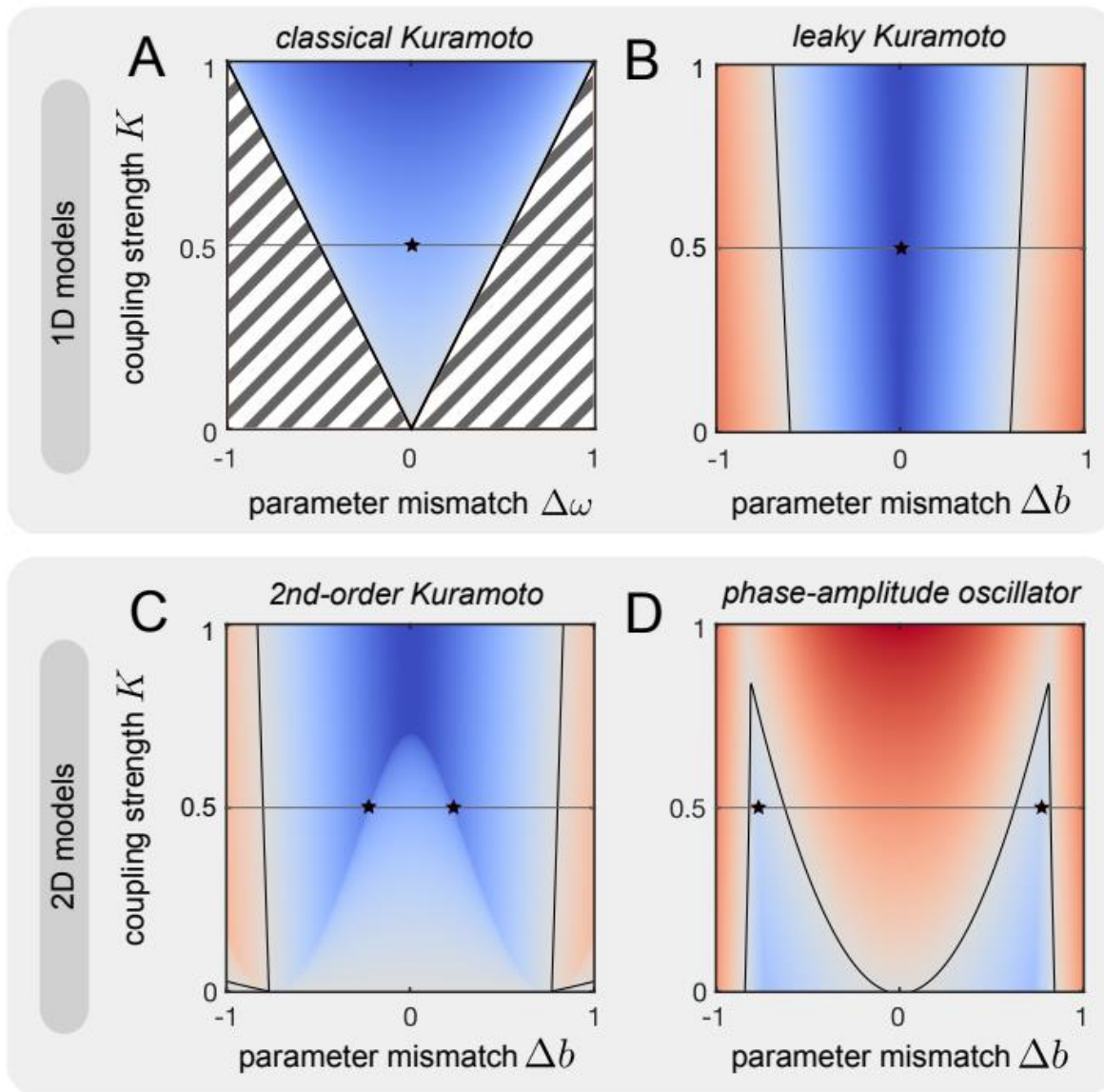
$$P^T A P = A$$

Given a network structure,
what is the optimal
parameter assignment
that maximizes stability?

Disorder-promoted stability: condition?



Disorder-promoted stability: condition?



Disorder-promoted stability: condition?

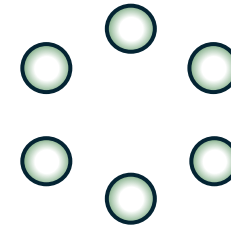
$$\delta \dot{\mathbf{x}} = \underbrace{J(\mathbf{b}; A)}_{\substack{\text{J is an affine function of } \mathbf{b}}} \Big|_{\mathbf{x}^{\text{eq}}} \delta \mathbf{x}$$

$$\mathbf{b}^* = \arg \min_{\mathbf{b}} \Lambda_{\max}(J(\mathbf{b}; A)) \quad \text{“stability enhancement”}$$

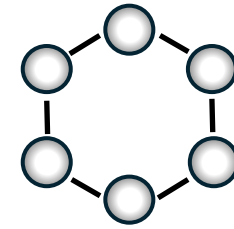
$$\dot{\mathbf{x}}_i = \mathbf{f}(\mathbf{x}_i; b_i) + \sum_{j=1}^N A_{ij} \mathbf{g}(\mathbf{x}_i, \mathbf{x}_j)$$

nodal
symmetries

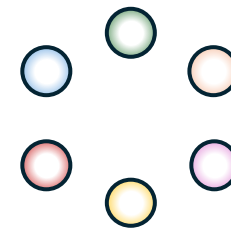
network
symmetries



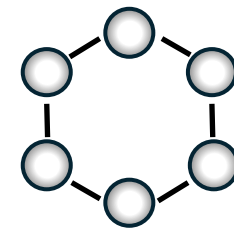
$$P\mathbf{b} = \mathbf{b}$$



$$P^T A P = A$$



$$P\mathbf{b} \neq \mathbf{b}$$



$$P^T A P = A$$

Disorder-promoted stability: condition?

$$\delta \dot{\mathbf{x}} = \underbrace{J(\mathbf{b}; A)}_{J \text{ is an affine function of } \mathbf{b}} \Big|_{\mathbf{x}^{\text{eq}}} \delta \mathbf{x}$$

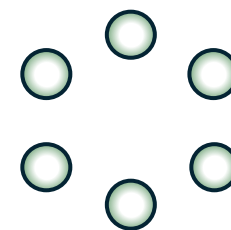
$$\mathbf{b}^* = \arg \min_{\mathbf{b}} \Lambda_{\max}(J(\mathbf{b}; A))$$

Theorem. If the optimization problem $\min_{\mathbf{b}} \Lambda_{\max}(J(\mathbf{b}; A))$ is convex, then \mathbf{b}^* must satisfy the network symmetries.

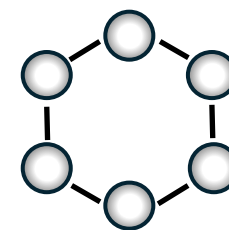
$$\dot{\mathbf{x}}_i = \mathbf{f}(\mathbf{x}_i; b_i) + \sum_{j=1}^N A_{ij} \mathbf{g}(\mathbf{x}_i, \mathbf{x}_j)$$

nodal symmetries

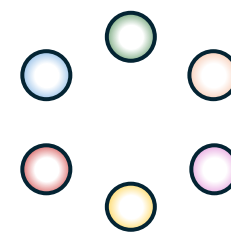
network symmetries



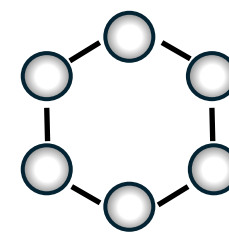
$$P\mathbf{b} = \mathbf{b}$$



$$P^T A P = A$$



$$P\mathbf{b} \neq \mathbf{b}$$



$$P^T A P = A$$

Disorder-promoted stability: condition?

$$\delta \dot{\mathbf{x}} = \underbrace{J(\mathbf{b}; A)}_{J \text{ is an affine function of } \mathbf{b}} \Big|_{\mathbf{x}^{\text{eq}}} \delta \mathbf{x}$$

$$\mathbf{b}^* = \arg \min_{\mathbf{b}} \Lambda_{\max}(J(\mathbf{b}; A))$$

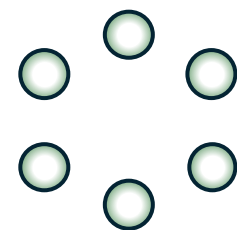
Theorem. If the optimization problem $\min_{\mathbf{b}} \Lambda_{\max}(J(\mathbf{b}; A))$ is convex, then \mathbf{b}^* must satisfy the network symmetries.

Corollary. If $J(\mathbf{b}; A)$ is non-Hermitian, then the optimization problem is non-convex for *almost all* networks.

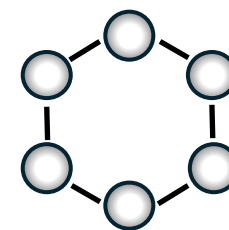
$$\dot{\mathbf{x}}_i = \mathbf{f}(\mathbf{x}_i; b_i) + \sum_{j=1}^N A_{ij} \mathbf{g}(\mathbf{x}_i, \mathbf{x}_j)$$

nodal symmetries

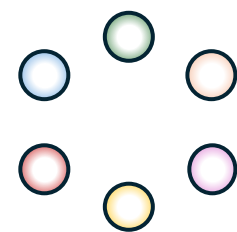
network symmetries



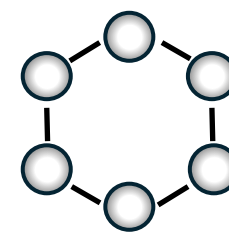
$$P\mathbf{b} = \mathbf{b}$$



$$P^T A P = A$$



$$P\mathbf{b} \neq \mathbf{b}$$



$$P^T A P = A$$

Disorder-promoted stability: condition?

$$\delta \dot{\mathbf{x}} = \underbrace{J(\mathbf{b}; A)}_{J \text{ is an affine function of } \mathbf{b}} \Big|_{\mathbf{x}^{\text{eq}}} \delta \mathbf{x}$$

$$\mathbf{b}^* = \arg \min_{\mathbf{b}} \Lambda_{\max}(J(\mathbf{b}; A))$$

Theorem. If the optimization problem $\min_{\mathbf{b}} \Lambda_{\max}(J(\mathbf{b}; A))$ is convex, then \mathbf{b}^* must satisfy the network symmetries.

Corollary. If $J(\mathbf{b}; A)$ is non-Hermitian, then the optimization problem is non-convex for *almost all* networks.

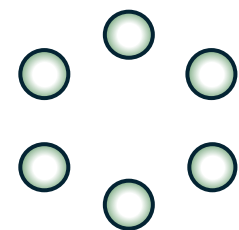
$$\dot{\mathbf{x}}_i = \mathbf{f}(\mathbf{x}_i; b_i) + \sum_{j=1}^N A_{ij} \mathbf{g}(\mathbf{x}_i, \mathbf{x}_j)$$

nodal symmetries

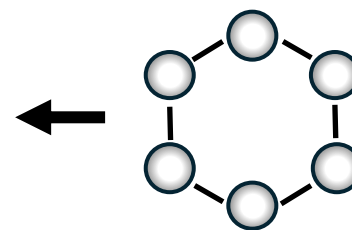
network symmetries

sufficiency

\mathbf{b}^* is homogeneous if $J(\mathbf{b}; A)$ is Hermitian.



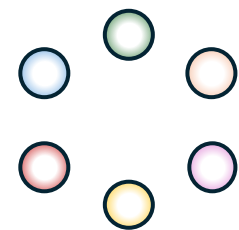
$$P\mathbf{b} = \mathbf{b}$$



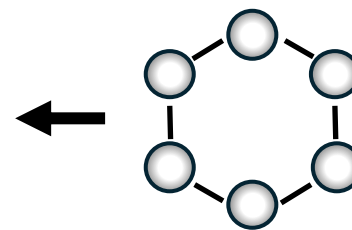
$$P^T A P = A$$

necessity

\mathbf{b}^* is heterogeneous only if $J(\mathbf{b}; A)$ is non-Hermitian.

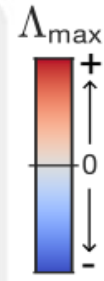
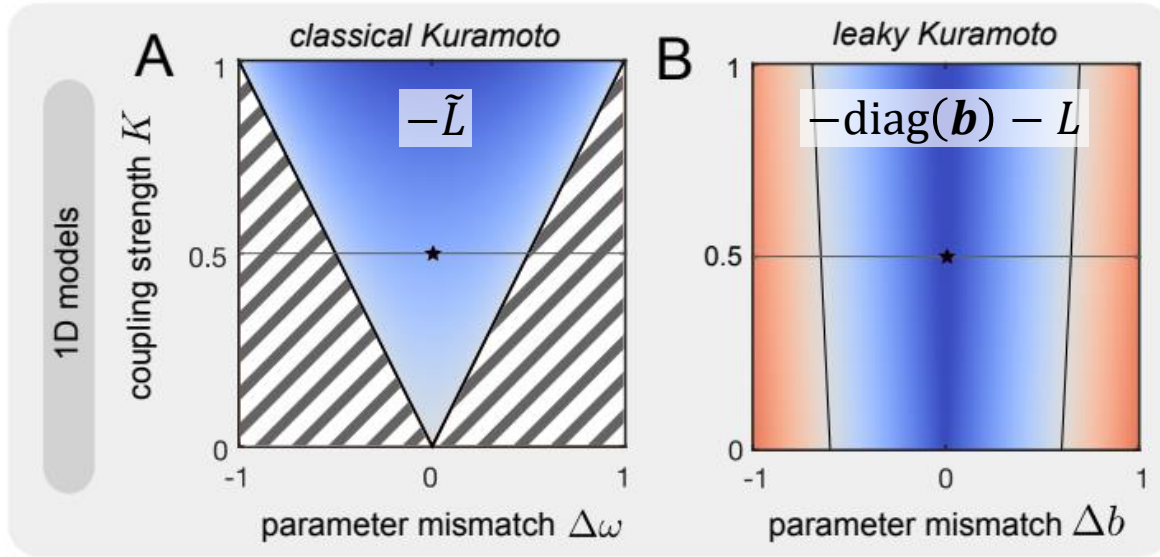


$$P\mathbf{b} \neq \mathbf{b}$$



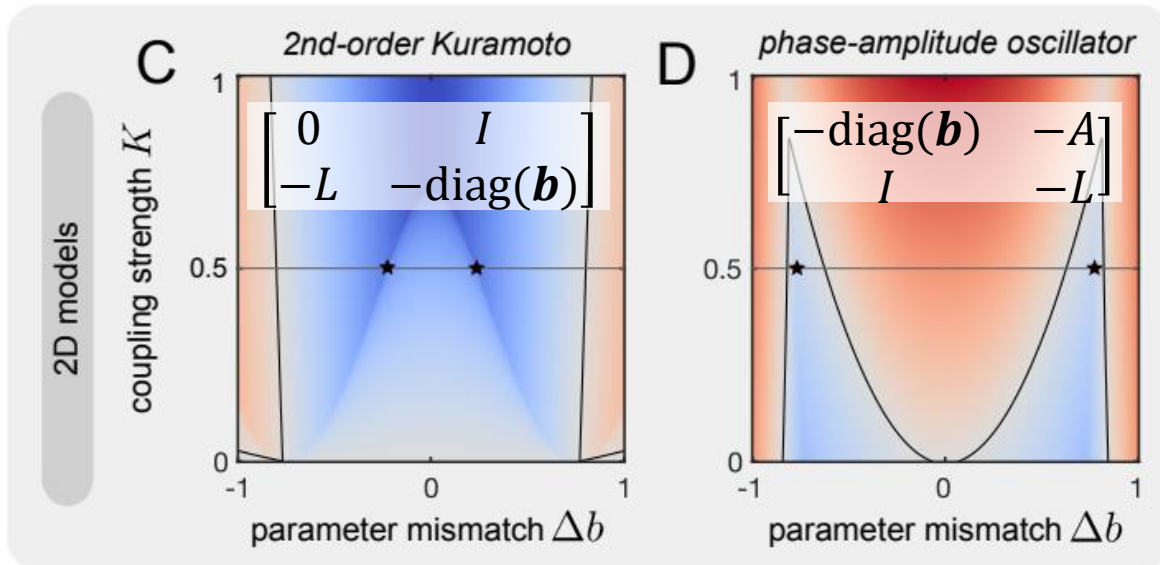
$$P^T A P = A$$

Disorder-promoted stability: condition?



sufficiency

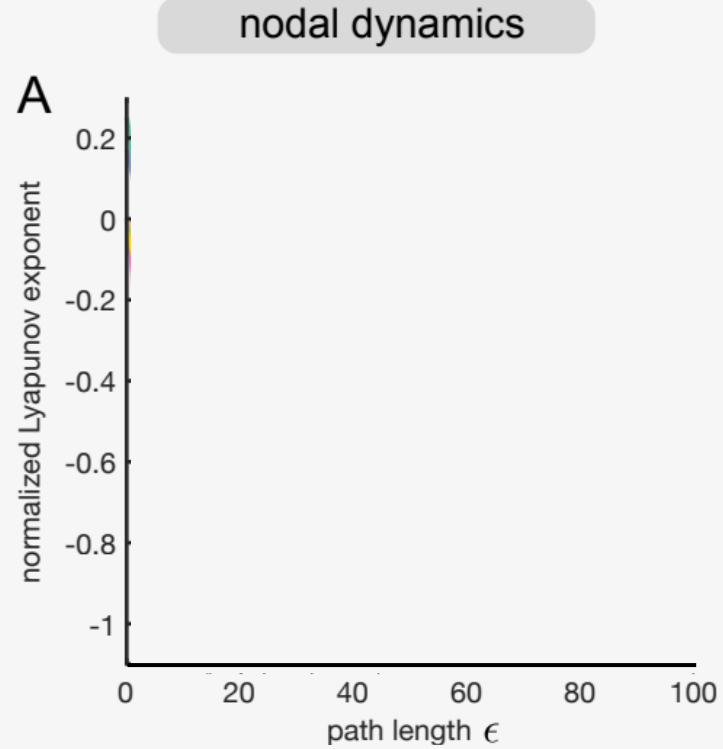
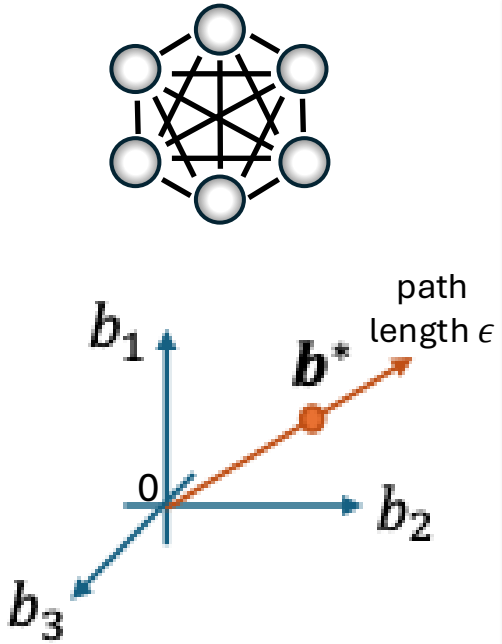
\mathbf{b}^* is homogeneous
if $J(\mathbf{b}; A)$ is Hermitian.



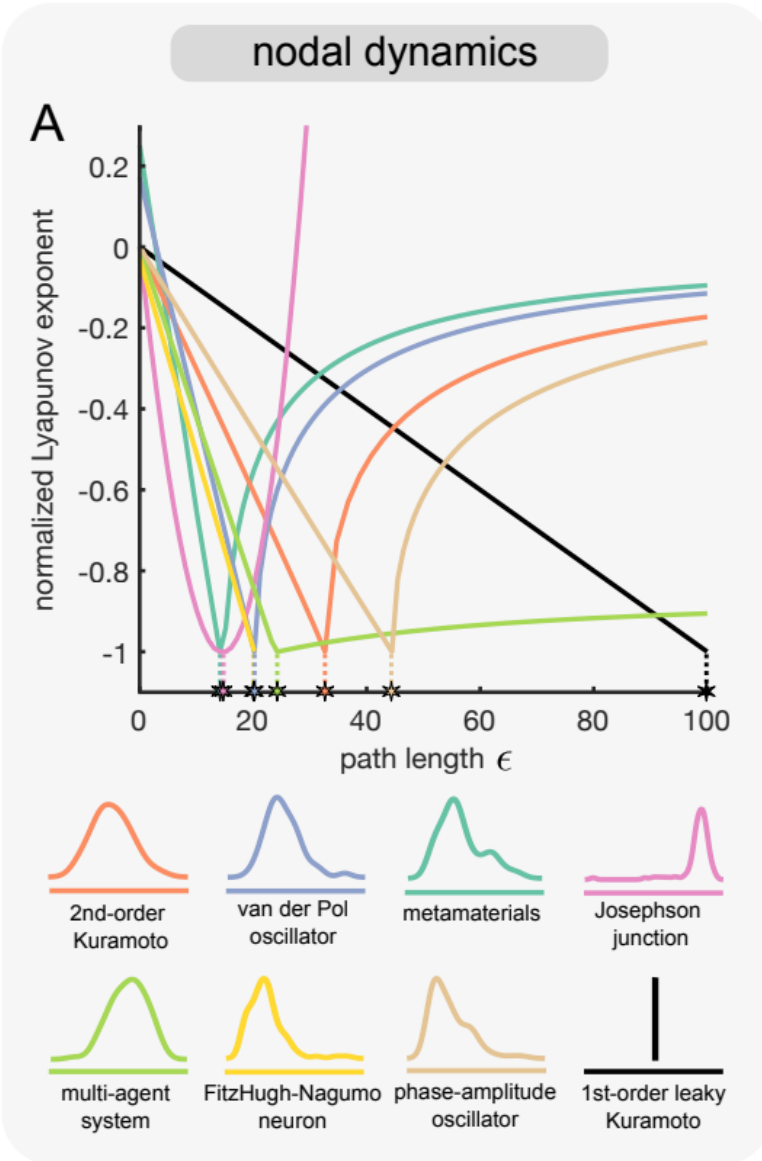
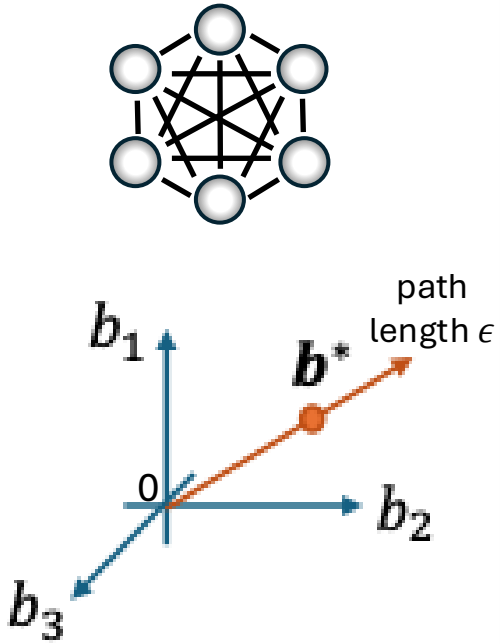
necessity

\mathbf{b}^* is heterogeneous
only if $J(\mathbf{b}; A)$ is
non-Hermitian.

Optimizing heterogeneity



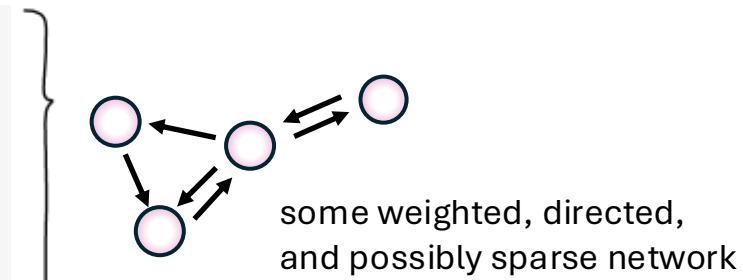
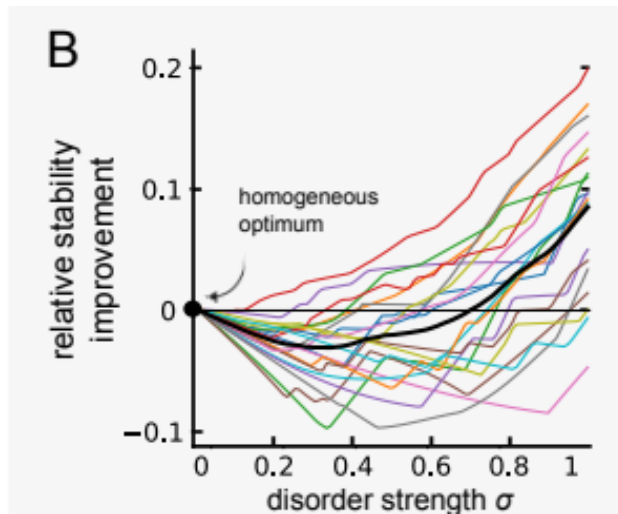
Optimizing heterogeneity



	System	Equations of motion	Jacobian matrix
first-order models	Leaky Kuramoto (synchronization)	$\dot{\phi}_i + b_i \phi_i = \omega + \sum_j A_{ij} \sin(\phi_j - \phi_i)$	$-(B + L)$
	Driven Kuramoto (pacemaker)	$\dot{\phi}_i + b_i \sin(\phi_i - \psi) = \omega + \sum_j A_{ij} \sin(\phi_j - \phi_i)$	$-(B + L)$
	Consensus (opinion, coordination)	$\dot{x}_i + b_i x_i = \sum_j A_{ij} (x_j - x_i)$	$-(B + L)$
second-order models	2nd-order Kuramoto (power grids)	$\ddot{\phi}_i + b_i \dot{\phi}_i = P + \sum_j A_{ij} \sin(\phi_j - \phi_i)$	$\begin{bmatrix} 0_N & I_N \\ -L & -B \end{bmatrix}$
	van der Pol (circuits, vibration)	$\ddot{x}_i + b_i (1 - x_i^2) \dot{x}_i + x_i = \sum_j A_{ij} (x_j - x_i)$	$\begin{bmatrix} 0_N & I_N \\ -(L + I_N) & -B \end{bmatrix}$
	Spring-mass system (materials)	$\ddot{x}_i + b_i \dot{x}_i + k x_i = \sum_j A_{ij} (x_j - x_i)$	$\begin{bmatrix} 0_N & I_N \\ -(L + k I_N) & -B \end{bmatrix}$
	Josephson junction (superconductors)	$\ddot{\phi}_i + b_i \dot{\phi}_i + I_c \sin(\phi_i) = I_b + \sum_j A_{ij} (\dot{\phi}_j - \dot{\phi}_i)$	$\begin{bmatrix} 0_N & I_N \\ -\sqrt{I_c^2 - I_b^2} I_N & -(L + B) \end{bmatrix}$
	Multi-agent system (flocking, navigation)	$\ddot{x}_i + b_i (\dot{x}_i - \dot{x}_i) + b_i (x_i - x_i) = \sum_j A_{ij} [(x_j - x_i) + (\dot{x}_j - \dot{x}_i)]$	$\begin{bmatrix} 0_N & I_N \\ -(L + B) & -(L + B) \end{bmatrix}$
2-dimensional models	FitzHugh-Nagumo (neurons)	$\dot{v}_i = v_i - \frac{v_i^3}{3} - w_i + \sum_j A_{ij} (v_j - v_i)$ $\tau \dot{w}_i = v_i + a - b_i w_i$	$\begin{bmatrix} -L + I_N - V^2 & -I_N \\ \tau^{-1} I_N & -\tau^{-1} B \end{bmatrix}$
	Phase-amplitude oscillator (lasers, circuits)	$\dot{r}_i = b_i r_i (1 - r_i) + \epsilon r_i \sum_j A_{ij} \cos(\phi_j - \phi_i)$ $\dot{\phi}_i = \omega + r_i - 1 + r_i \sum_j A_{ij} \sin(\phi_j - \phi_i)$	$\begin{bmatrix} -B & -\epsilon A \\ I_N & -L \end{bmatrix}$

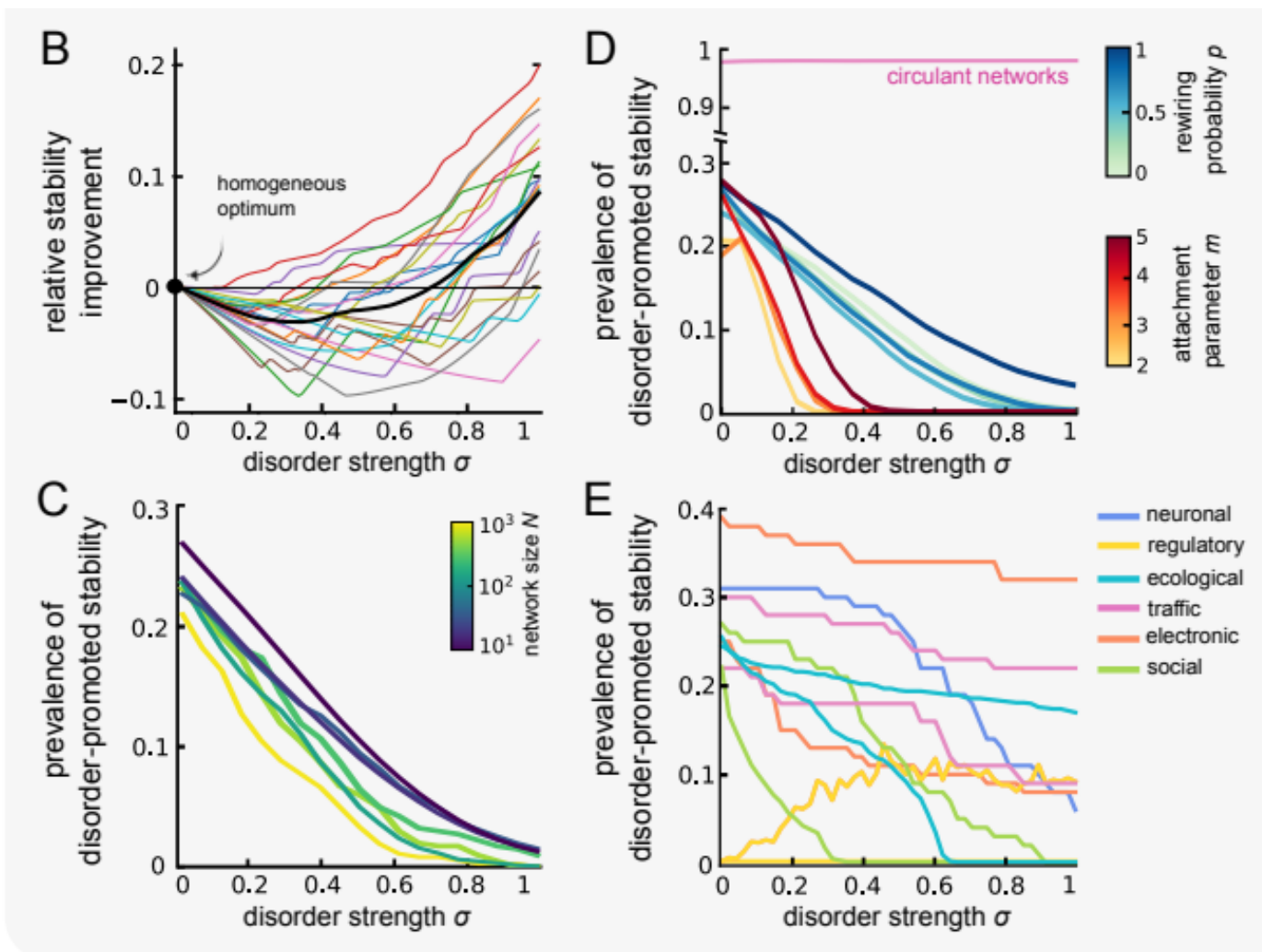
Disorder-promoted stability

*now the analysis is for disordered parameters, so that $b_i \sim \mathcal{N}(\mu, \sigma^2)$



Disorder-promoted stability

*now the analysis is for disordered parameters, so that $b_i \sim \mathcal{N}(\mu, \sigma^2)$



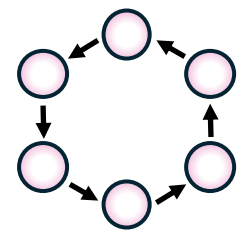
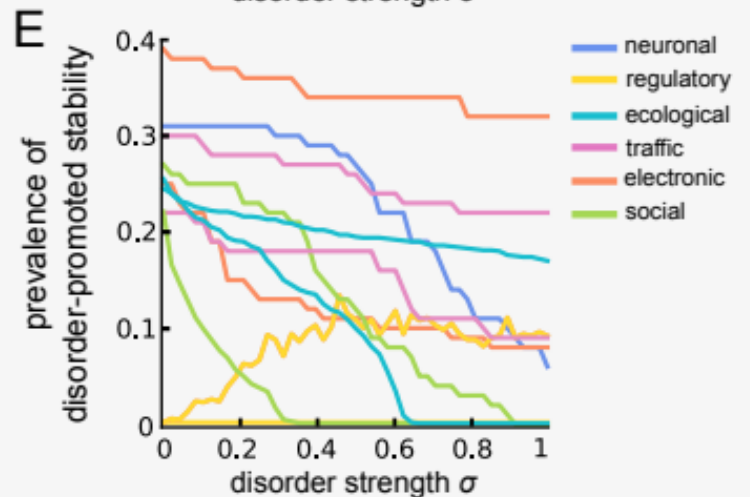
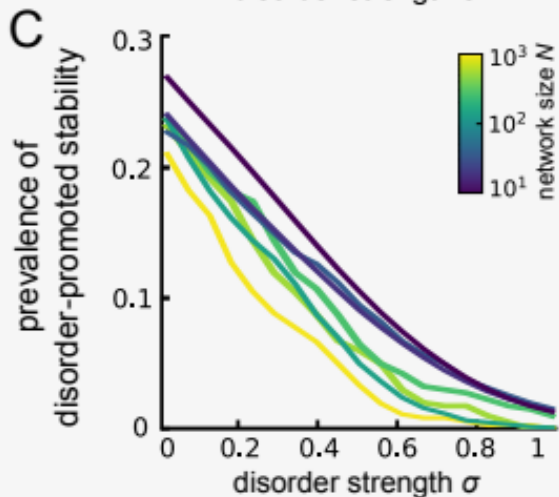
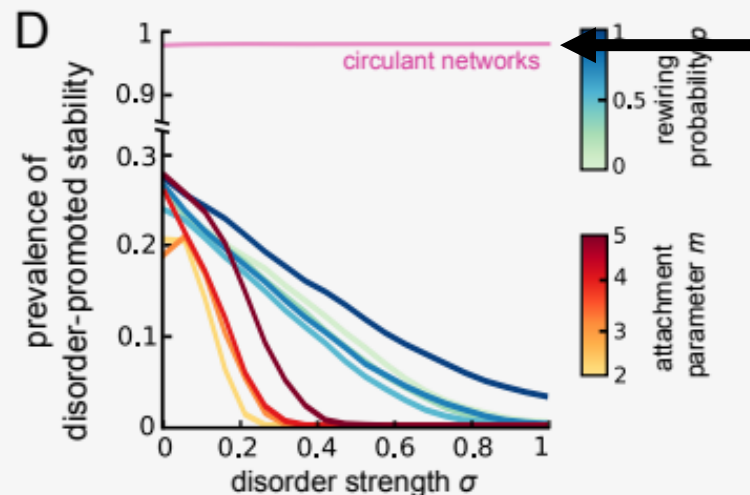
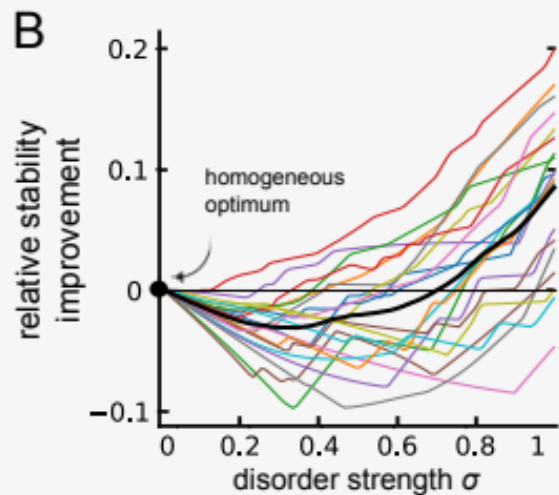
directed small-world networks

directed scale-free networks

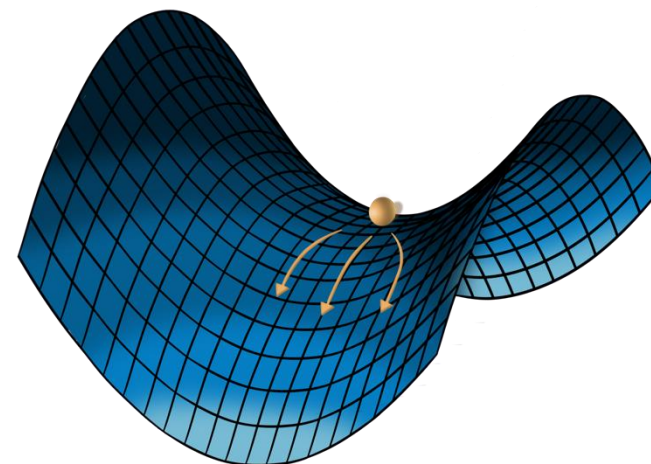
directed empirical networks

Disorder-promoted stability

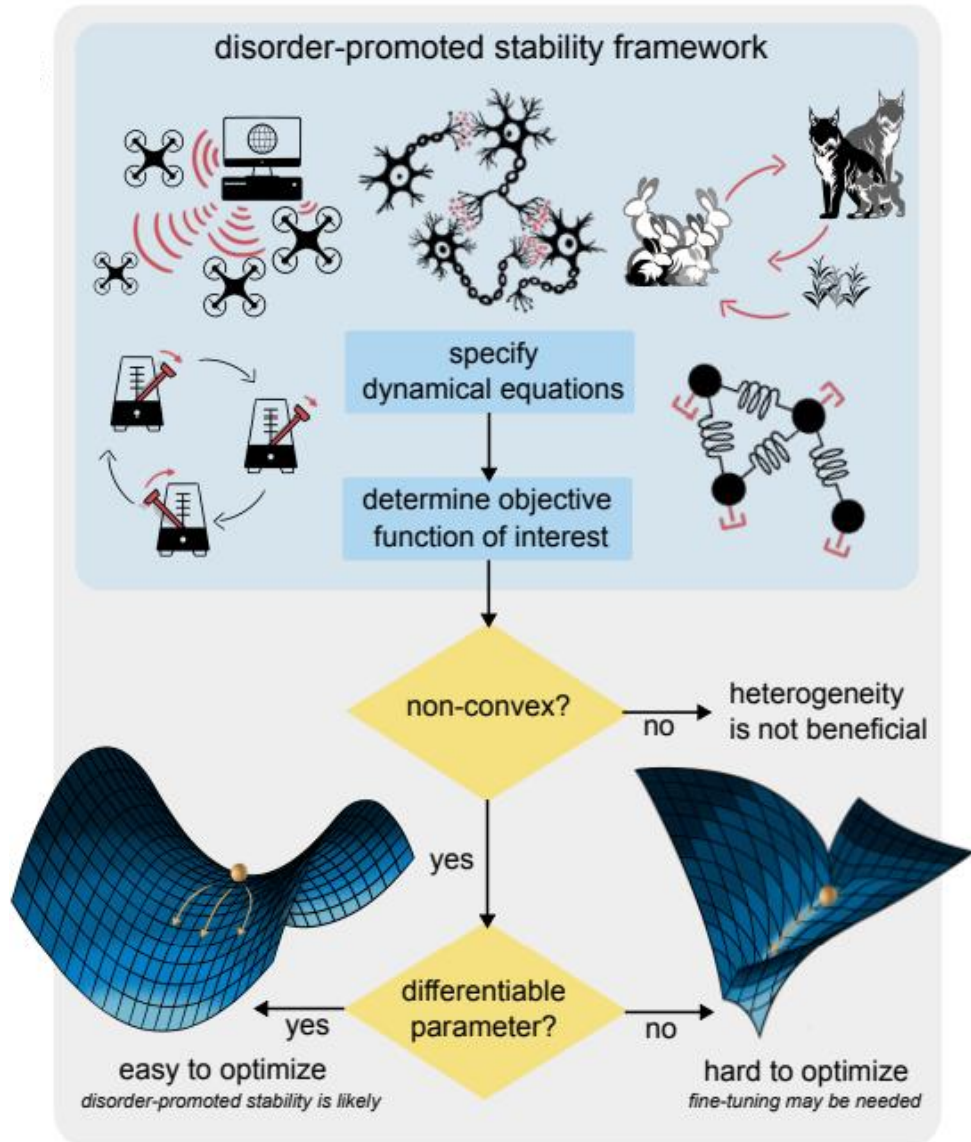
*now the analysis is for disordered parameters, so that $b_i \sim \mathcal{N}(\mu, \sigma^2)$



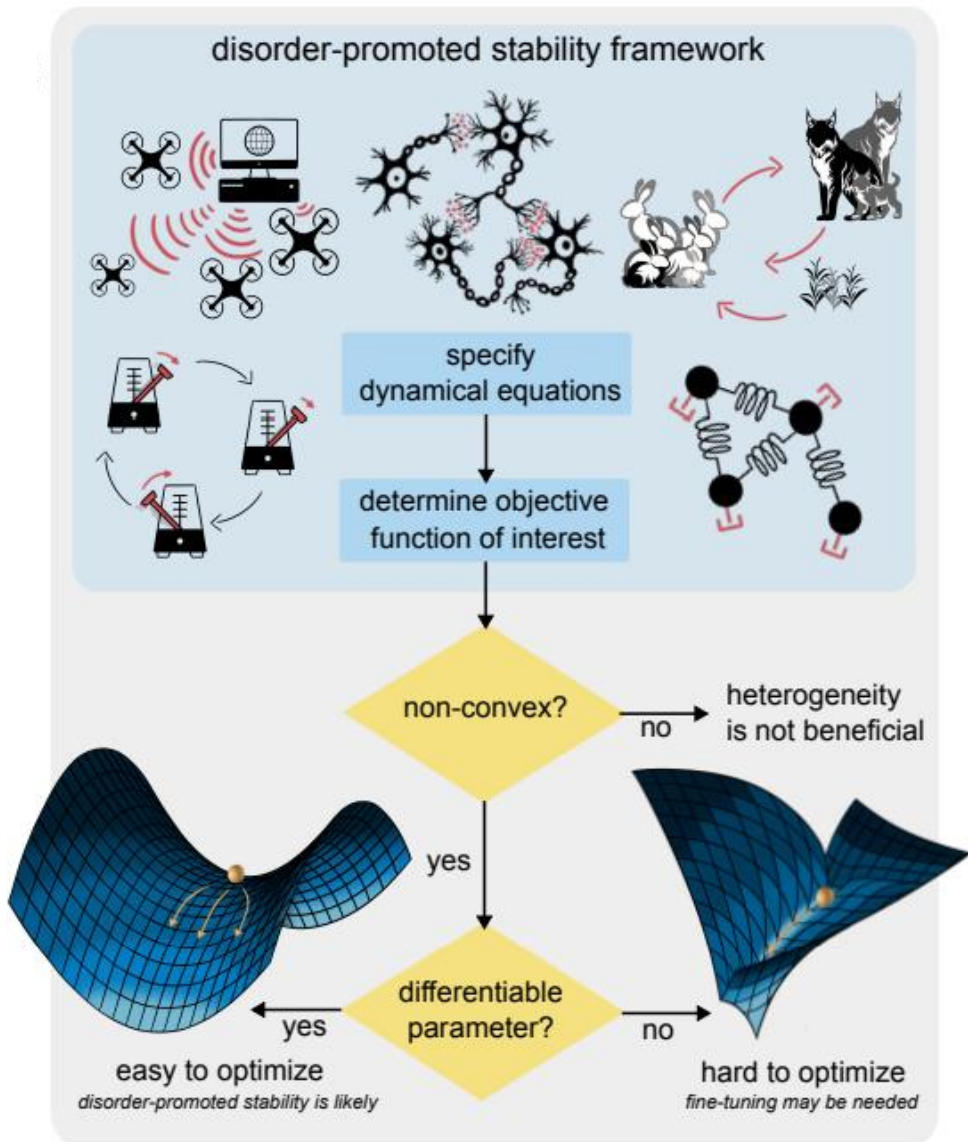
homogeneous optimal parameter \mathbf{b}^* is differentiable and a saddle point



The framework



The framework



PNAS

RESEARCH ARTICLE | APPLIED PHYSICAL SCIENCES |



Random heterogeneity outperforms design in network synchronization

Yuanzhao Zhang , Jorge L. Ocampo-Espindola , István Z. Kiss, and Adilson E. Motter [Authors Info & Affiliations](#)

PNAS

RESEARCH ARTICLE | NEUROSCIENCE

OPEN ACCESS

Neural heterogeneity controls computations in spiking neural networks

Richard Gast^{a,b,1} , Sara A. Solla^a , and Ann Kennedy^{ab}

LETTERS TO NATURE Taming spatiotemporal chaos with disorder

Y. Braiman^{*†}, John F. Lindner^{*‡}
& William L. Ditto^{*}

^{*} Applied Chaos Laboratory, School of Physics, Georgia Institute of Technology, Atlanta, Georgia 30332, USA
[†] The College of Wooster, Wooster, Ohio 44691, USA

nature communications

Article

Emergent microrobotic oscillators via asymmetry-induced order

PHYSICAL REVIEW RESEARCH 7, 013207 (2025)

Social network heterogeneity promotes depolarization of multidimensional correlated opinions

Jaume Ojer ,¹ Michele Starnini ,^{2,3,*} and Romualdo Pastor-Satorras^{1,†}

PRX ENERGY 3, 033003 (2024)

Stabilizing Large-Scale Electric Power Grids with Adaptive Inertia

Julian Fritzsche^{1,2,*} and Philippe Jacquod^{1,2,†}

¹ Department of Quantum Matter Physics, University of Geneva, Geneva CH-1211, Switzerland

² School of Engineering, University of Applied Sciences of Western Switzerland, Haute Ecole Spécialisée de Suisse occidentale (HES-SO), Sion CH-1950, Switzerland

The framework: Coupled-laser arrays

disorder-promoted stability framework

$$\dot{r}_j(t) = \frac{1}{2}(G_j - \gamma)r_j(t) + \kappa_j \sum_{k=1}^M A_{jk} r_k(t - \tau) \cos \Phi_{jk},$$

$$\dot{\phi}_j(t) = \frac{\alpha_j}{2}(G_j - \gamma) + \omega_j + \kappa_j \sum_{k=1}^M A_{jk} \frac{r_k(t - \tau)}{r_j(t)} \sin \Phi_{jk},$$

$$\dot{N}_j(t) = J_0 - \gamma_n N_j(t) - G_j r_j^2(t),$$

determine objective function of interest

non-convex?

no

heterogeneity is not beneficial

yes

differentiable parameter?

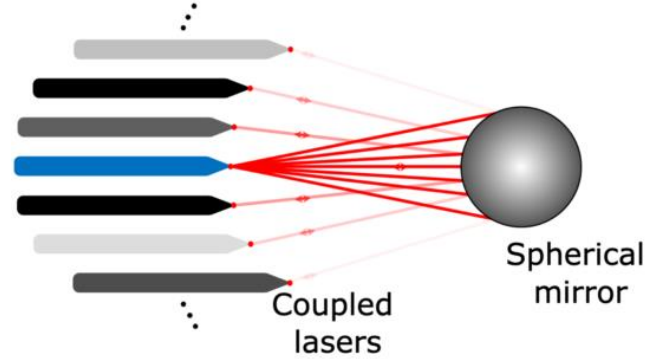
no

easy to optimize

disorder-promoted stability is likely

hard to optimize

fine-tuning may be needed



Barioni, **ANM**, Motter. *PRL* (2025).

The framework: Coupled-laser arrays

disorder-promoted stability framework

$$\dot{r}_j(t) = \frac{1}{2}(G_j - \gamma)r_j(t) + \kappa_j \sum_{k=1}^M A_{jk} r_k(t - \tau) \cos \Phi_{jk},$$

$$\dot{\phi}_j(t) = \frac{\alpha_j}{2}(G_j - \gamma) + \omega_j + \kappa_j \sum_{k=1}^M A_{jk} \frac{r_k(t - \tau)}{r_j(t)} \sin \Phi_{jk},$$

$$\dot{N}_j(t) = J_0 - \gamma_n N_j(t) - G_j r_j^2(t),$$

determine objective function of interest

non-convex?

no → heterogeneity is not beneficial

yes

differentiable parameter?

yes

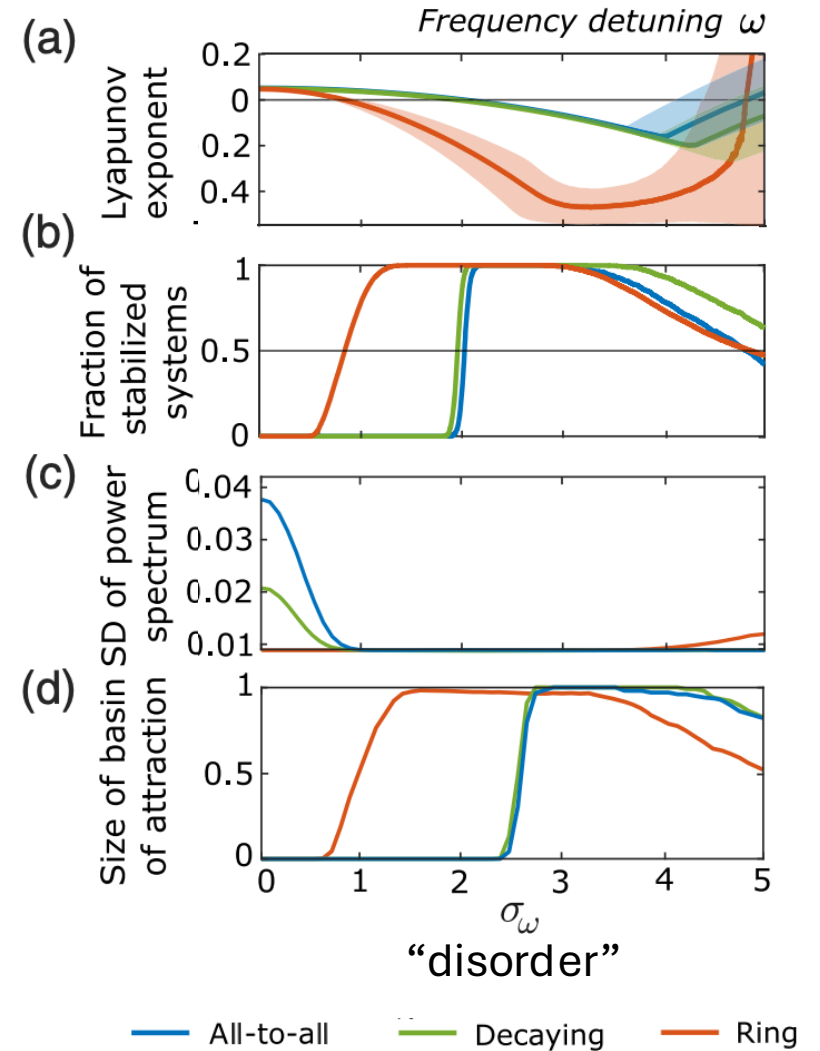
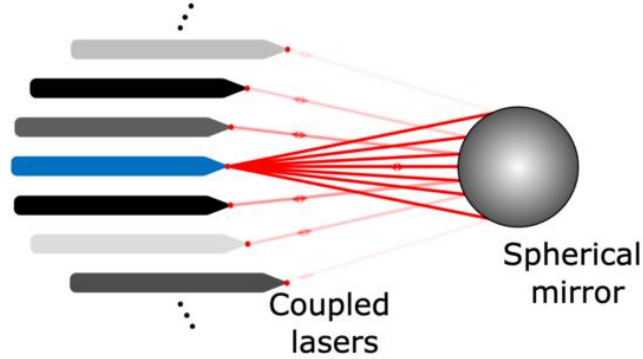
no

easy to optimize

disorder-promoted stability is likely

hard to optimize

fine-tuning may be needed



Barioni, **ANM**, Motter. *PRL* (2025).

The framework: Optimal flocking

disorder-promoted stability framework

$$\begin{aligned} \dot{\mathbf{q}}_i &= \mathbf{p}_i, \\ \dot{\mathbf{p}}_i &= \dot{\mathbf{p}}_t - b_i(\mathbf{q}_i - \mathbf{q}_t - \mathbf{r}_i) - \gamma c_i(\mathbf{p}_i - \mathbf{p}_t) \\ &\quad + \sum_{j=1}^N A_{ij}(t) [(\mathbf{q}_j - \mathbf{r}_j) - (\mathbf{q}_i - \mathbf{r}_i) + \gamma(\mathbf{p}_j - \mathbf{p}_i)] \end{aligned}$$

determine objective function of interest

non-convex?

no → heterogeneity is not beneficial

yes

differentiable parameter?

yes

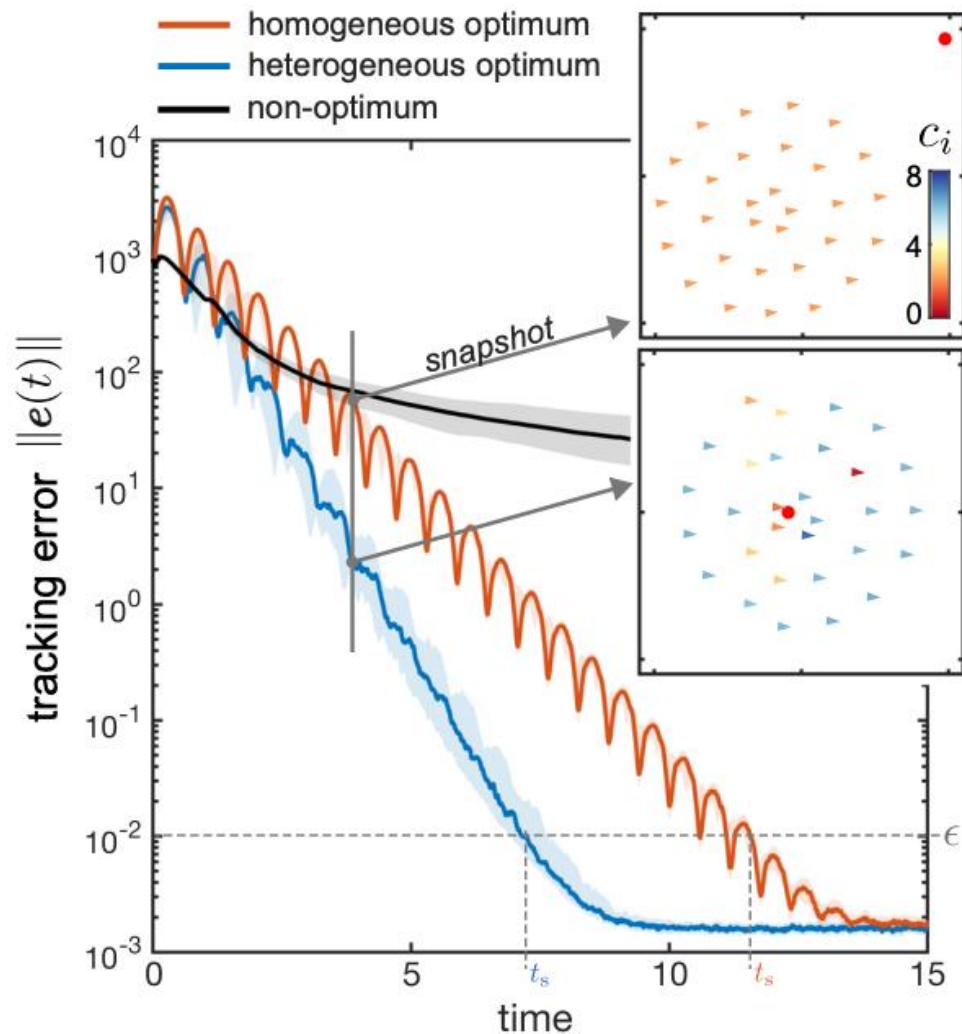
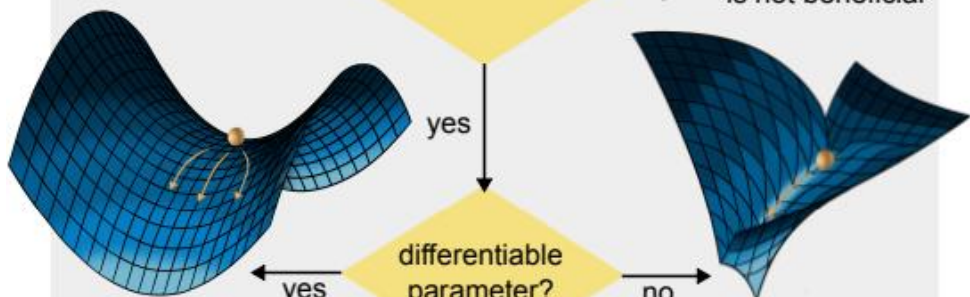
easy to optimize

disorder-promoted stability is likely

no

hard to optimize

fine-tuning may be needed

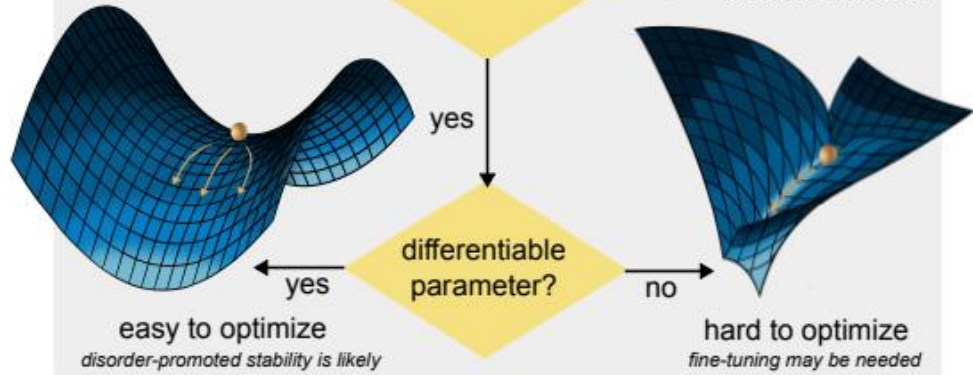
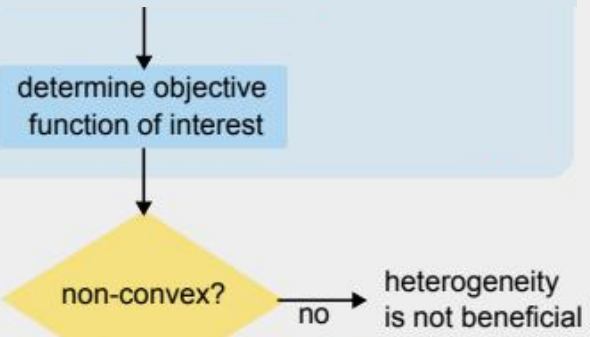


ANM, Barioni, Duan, Motter. *Nature Communications* (2025).

The framework: Optimal flocking

disorder-promoted stability framework

$$\begin{aligned}\dot{\mathbf{q}}_i &= \mathbf{p}_i, \\ \dot{\mathbf{p}}_i &= \dot{\mathbf{p}}_t - b_i(\mathbf{q}_i - \mathbf{q}_t - \mathbf{r}_i) - \gamma c_i(\mathbf{p}_i - \mathbf{p}_t) \\ &\quad + \sum_{j=1}^N A_{ij}(t) [(\mathbf{q}_j - \mathbf{r}_j) - (\mathbf{q}_i - \mathbf{r}_i) + \gamma(\mathbf{p}_j - \mathbf{p}_i)]\end{aligned}$$

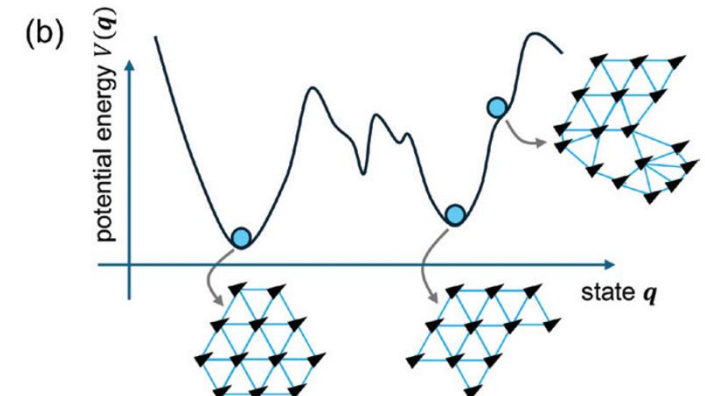
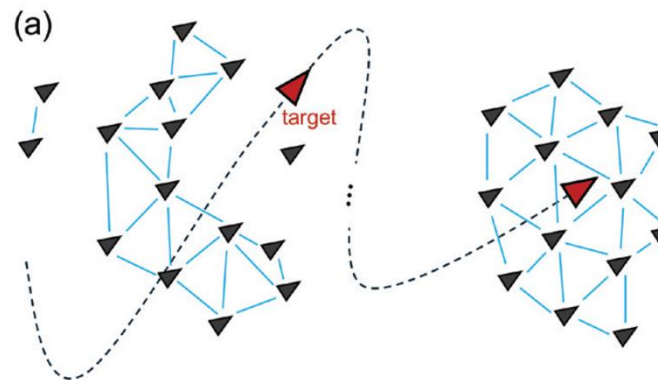


Heterogeneity for Flocking and Computation: From Biology to Mathematics

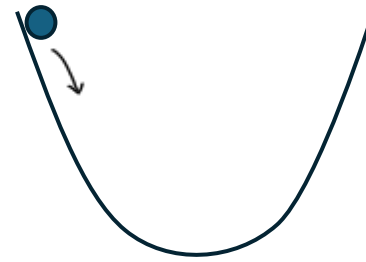
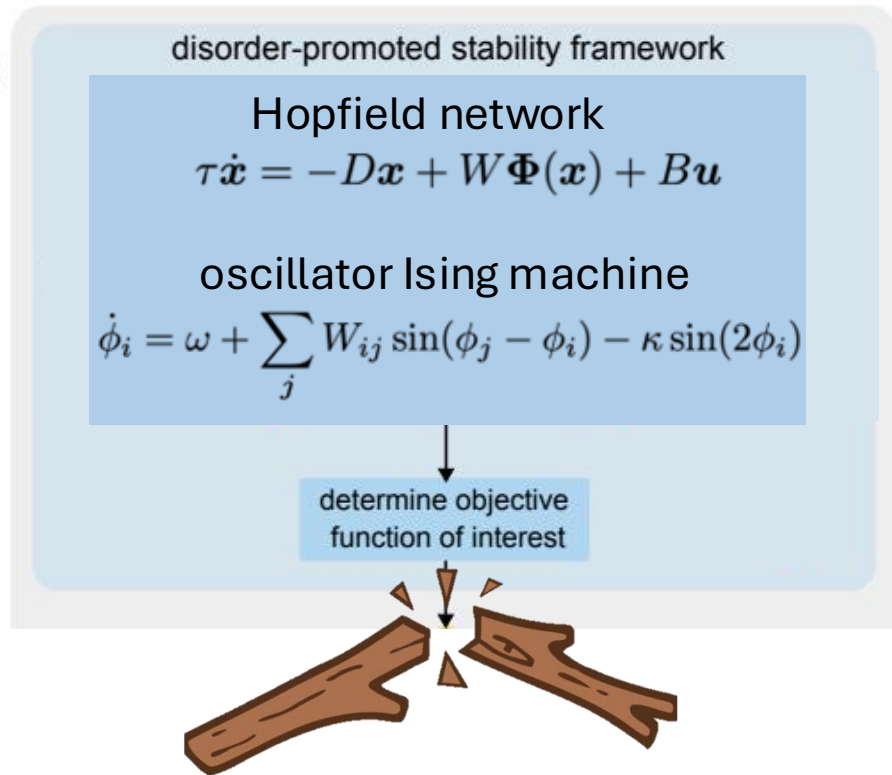
By Arthur N. Montanari,
Ana Elisa D. Barioni,
and Adilson E. Motter



Art by
Camila Montanari

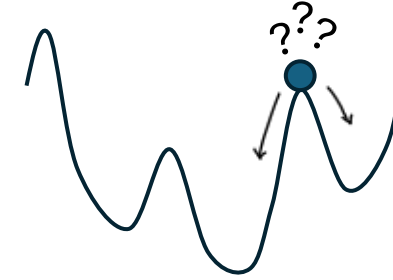


The framework: Neurocomputation



stabilization
synchronization

vs



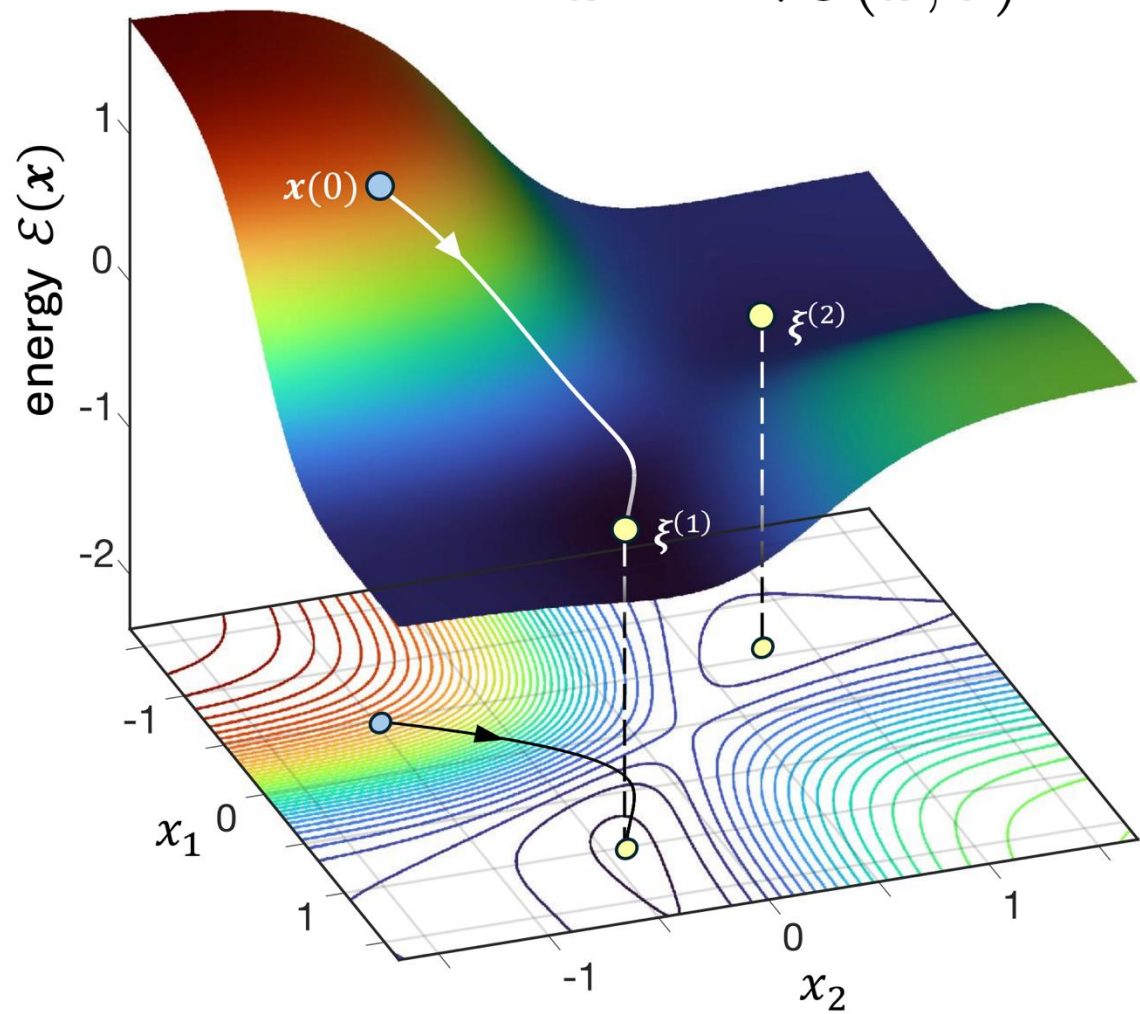
computation
decision-making

Part I: Disorder & Stability

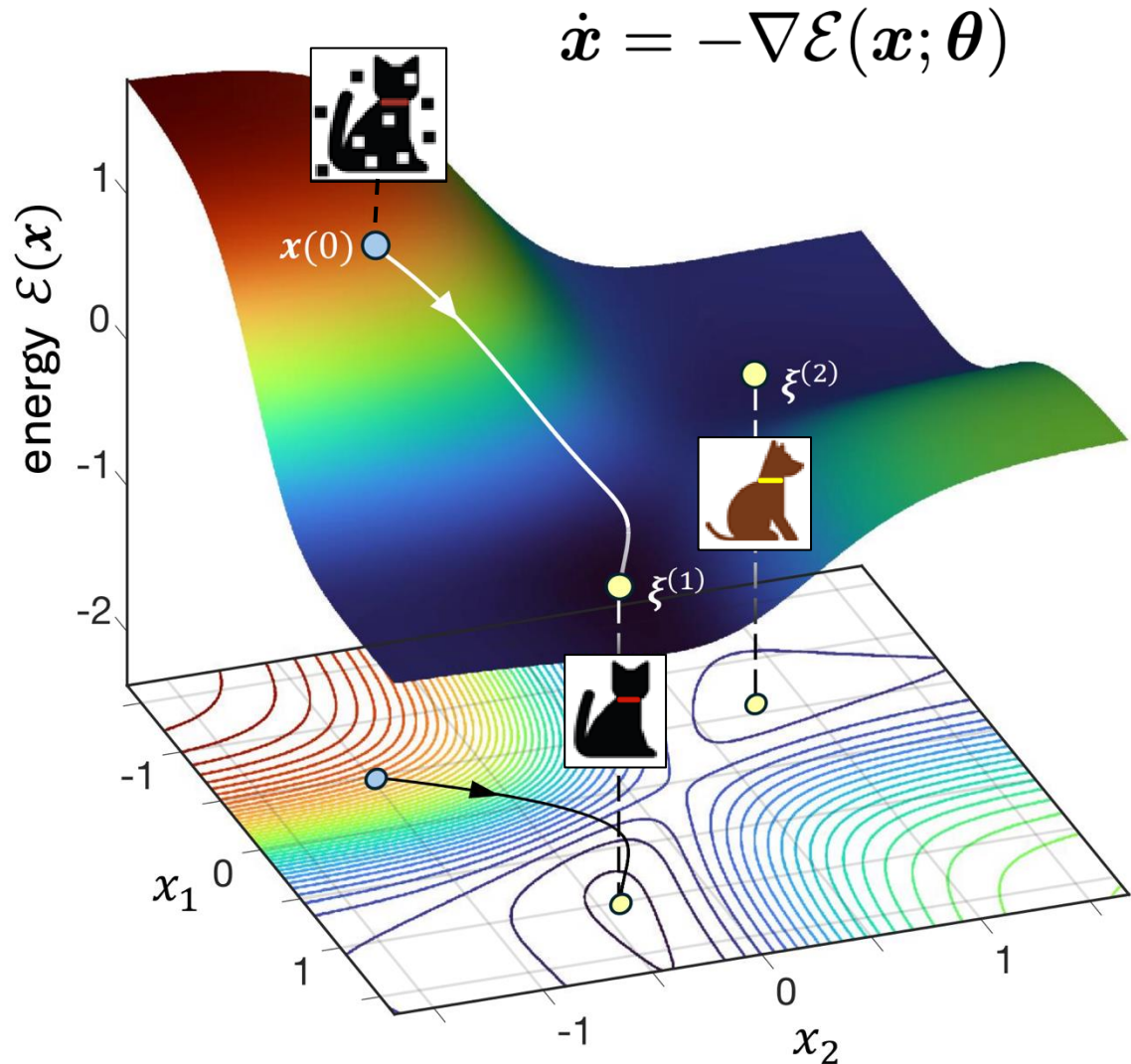
Part II: Disorder & Computation

Energy-based dynamical models

$$\dot{x} = -\nabla \mathcal{E}(x; \theta)$$



Energy-based dynamical models



Hopfield network

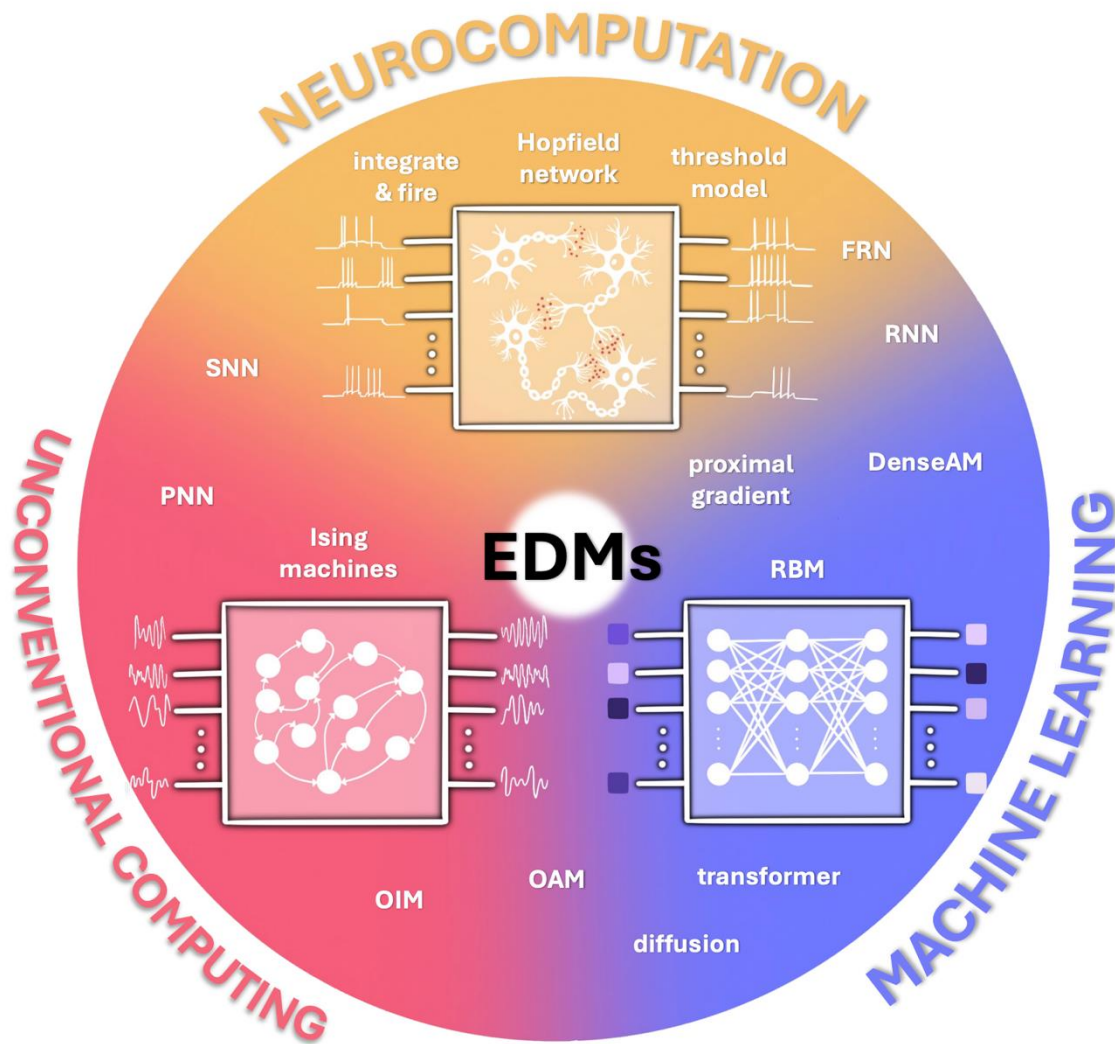
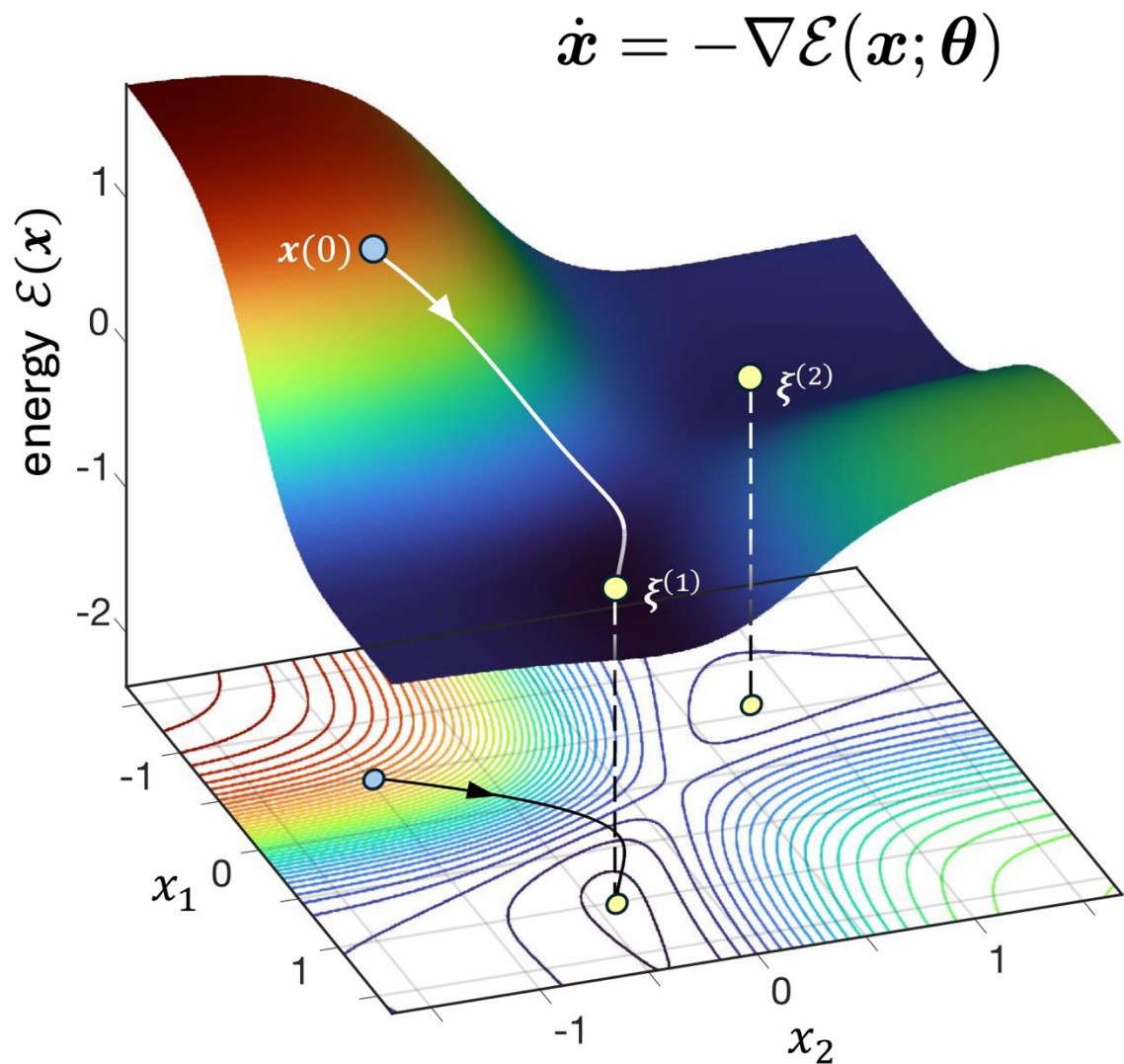
$$\dot{\mathbf{x}} = -\nabla \mathcal{E}(\mathbf{x}; W)$$

$$\tau \dot{\mathbf{x}} = -D\mathbf{x} + W\boldsymbol{\Phi}(\mathbf{x}) + B\mathbf{u}$$

Ising machine

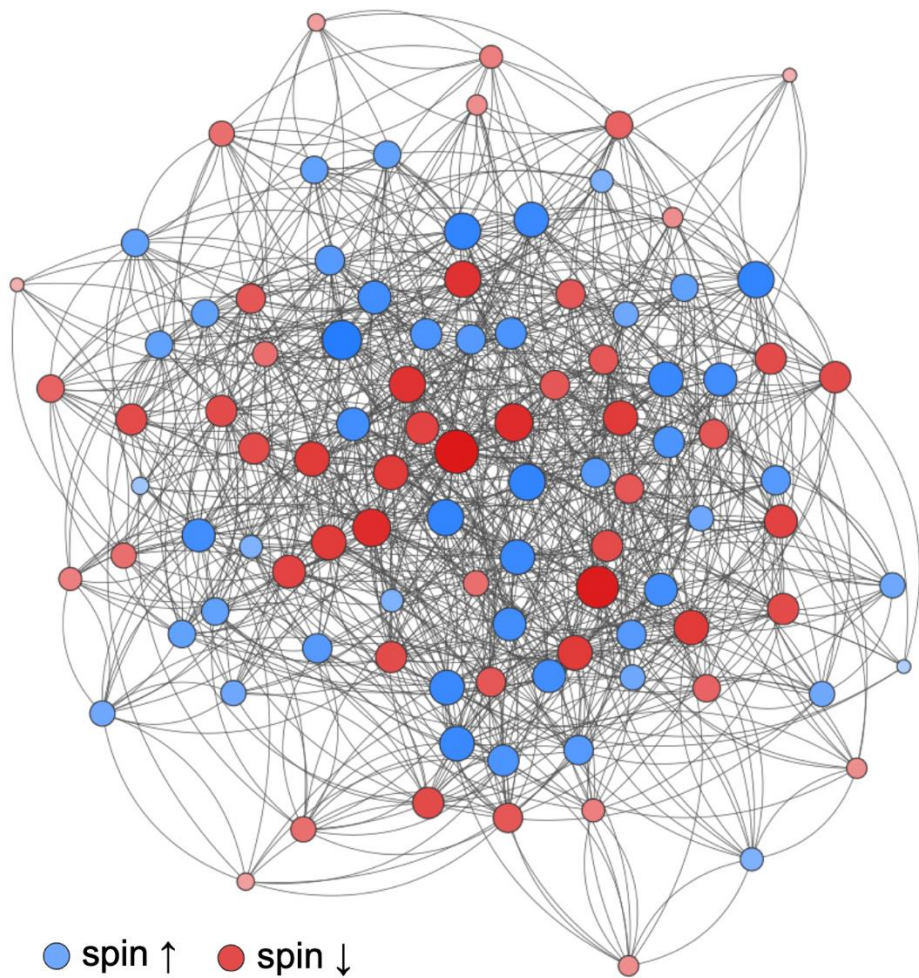
$\dot{\boldsymbol{\theta}}$ = gradient descent on the Ising Hamiltonian

Energy-based dynamical models



ANM, Bullo, Krotov, Motter. ACC (2026).
 American Control Conference (tutorial).
 arXiv:2604.05042

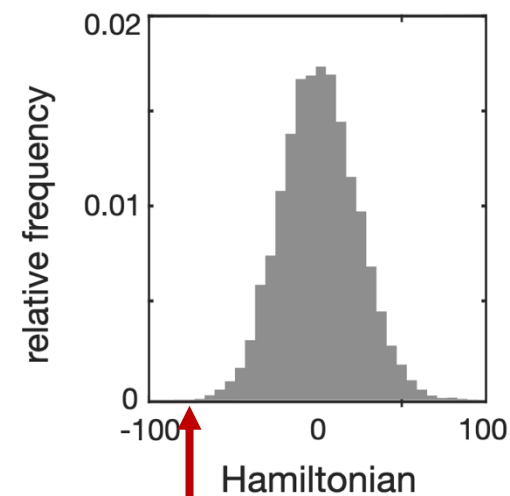
Ising optimization problem



Ising Hamiltonian:
$$H(\mathbf{s}) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} s_i s_j, \quad s_i \in \{-1, +1\}$$

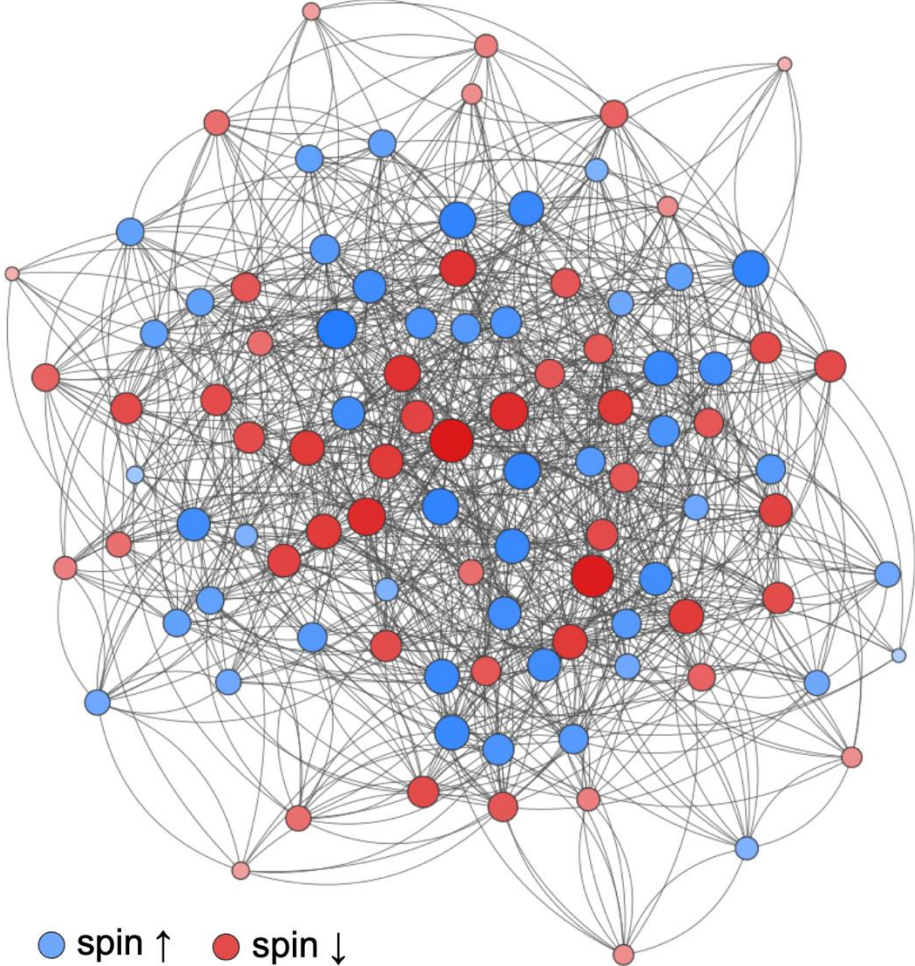


Ising optimization problem:
$$\min_{\mathbf{s}} H(\mathbf{s})$$



global minimizer \mathbf{s}^*

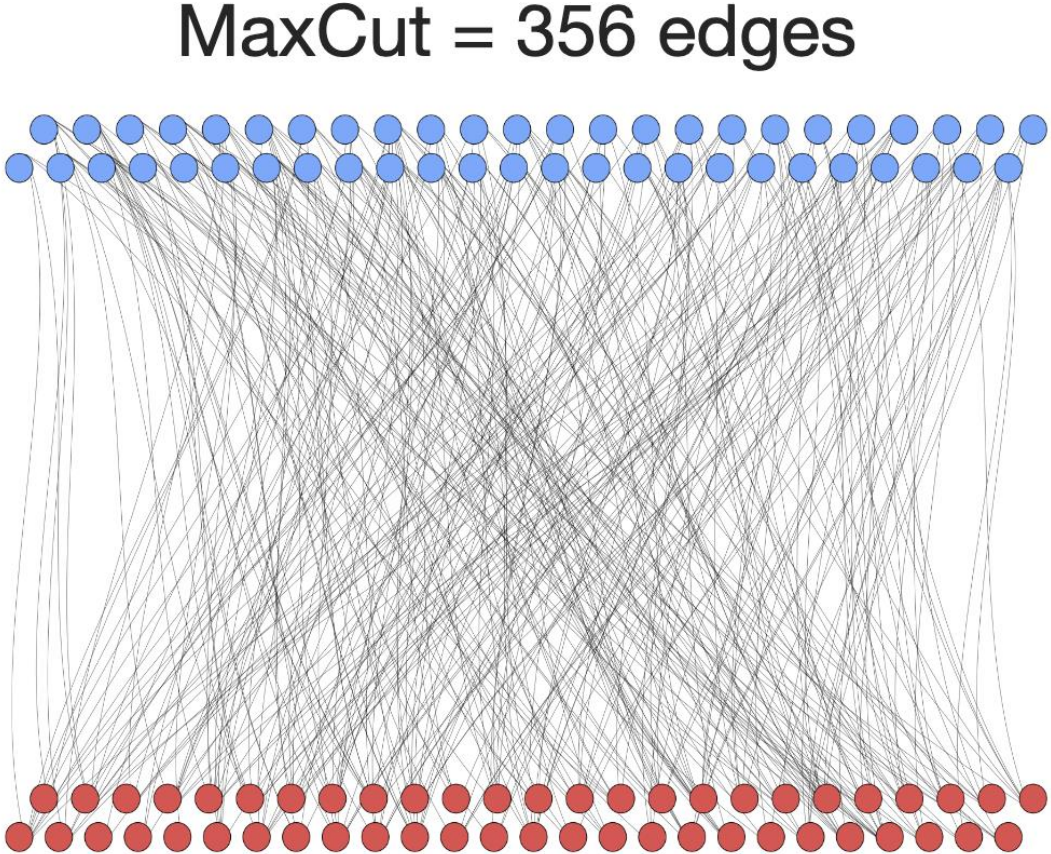
Ising optimization problem



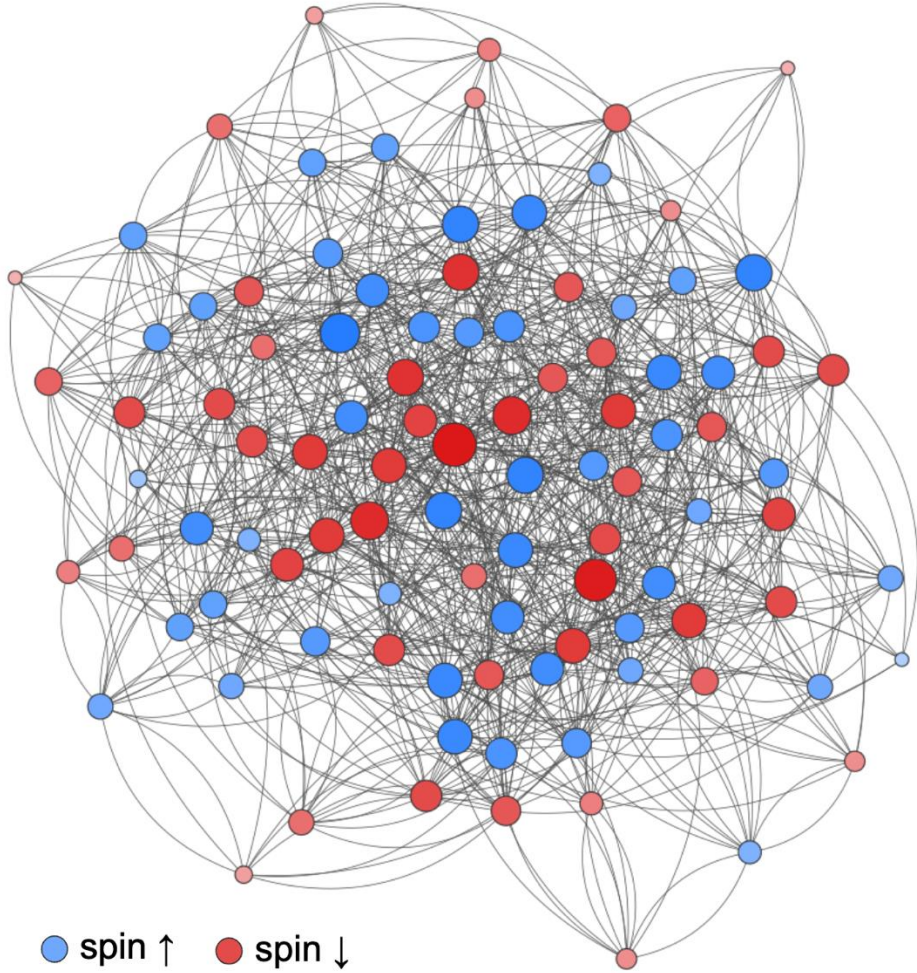
???

→

2^N possible solutions



Ising machines



Ising Hamiltonian: $H(\mathbf{s}) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} s_i s_j, s_i \in \{-1, +1\}$

Ising optimization problem: $\min_{\mathbf{s}} H(\mathbf{s})$

Ising machine (EDM): $\dot{\boldsymbol{\theta}} = -\nabla E(\boldsymbol{\theta})$

$$E(\boldsymbol{\theta}) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} \cos(\theta_i - \theta_j) + \sum_{i=1}^N \mu_i \sin(\theta_i)^2$$

$$\theta_i^*(\mathbf{s}) = \begin{cases} 0, & \text{if } s_i = +1, \\ \pi, & \text{if } s_i = -1, \end{cases}$$

Oscillator Ising machines

Ising Hamiltonian: $H(\mathbf{s}) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} s_i s_j$, $s_i \in \{-1, +1\}$

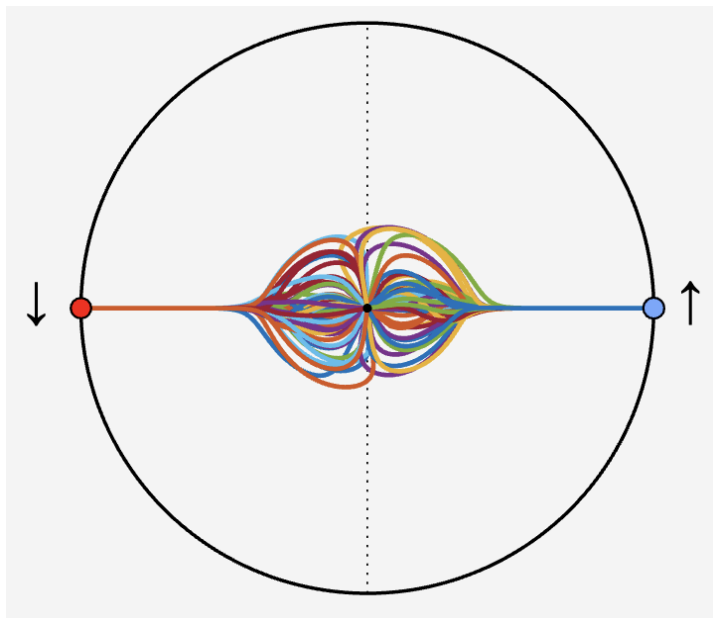
Ising optimization problem: $\min_{\mathbf{s}} H(\mathbf{s})$

Ising machine (EDM): $\dot{\boldsymbol{\theta}} = -\nabla E(\boldsymbol{\theta})$

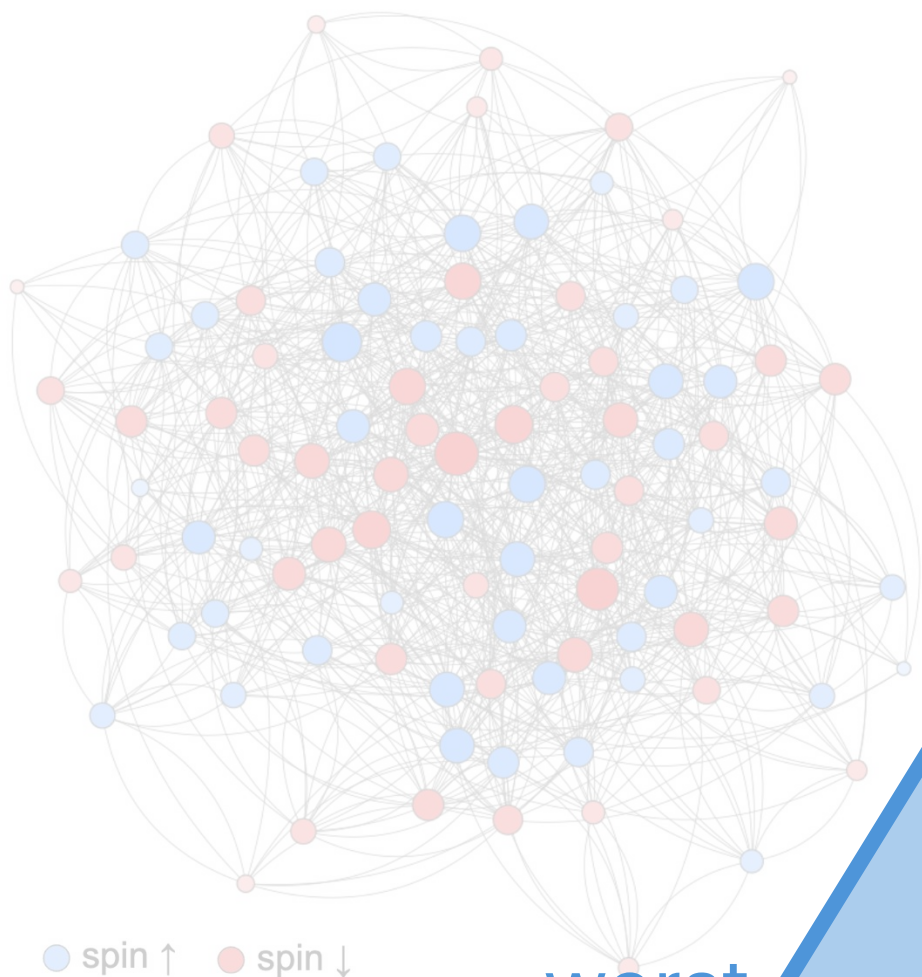
$E(\boldsymbol{\theta}) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} \cos(\theta_i - \theta_j) + \sum_{i=1}^N \mu_i \sin(\theta_i)^2$

Oscillator Ising machine (OIM): $\dot{\theta}_i = \sum_{j=1}^N J_{ij} \sin(\theta_j - \theta_i) - \mu_i \sin(2\theta_i)$

$$\theta_i^*(\mathbf{s}) = \begin{cases} 0, & \text{if } s_i = +1, \\ \pi, & \text{if } s_i = -1, \end{cases}$$



Oscillator Ising machines



worst

Ising Hamiltonian: $H(\mathbf{s}) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} s_i s_j, s_i \in \{-1, +1\}$

real

Ising optimization problem: $\min_{\mathbf{s}} H(\mathbf{s})$

Ising machine (EDM): $\dot{\theta} = -\nabla E(\theta)$

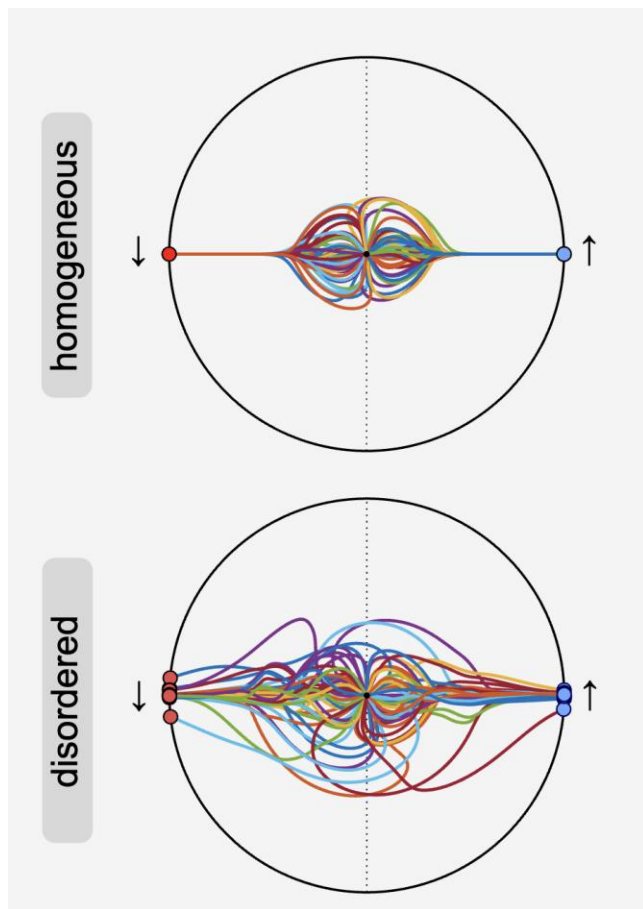
$E(\theta) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} \cos(\theta_i - \theta_j) + \sum_{i=1}^N \mu_i \sin(\theta_i)^2$

$\theta_i^*(\mathbf{s}) = \begin{cases} 0, & \text{if } s_i = +1, \\ \pi, & \text{if } s_i = -1, \end{cases}$

Oscillator Ising machine (OIM): $\dot{\theta}_i = \sum_{j=1}^N J_{ij} \sin(\theta_j - \theta_i) - \mu_i \sin(2\theta_i)$

random

Disordered oscillator Ising machines



Ising Hamiltonian: $H(\mathbf{s}) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} s_i s_j, s_i \in \{-1, +1\}$

Ising optimization problem: $\min_{\mathbf{s}} H(\mathbf{s})$

Ising machine (EDM): $\dot{\boldsymbol{\theta}} = -\nabla E(\boldsymbol{\theta})$

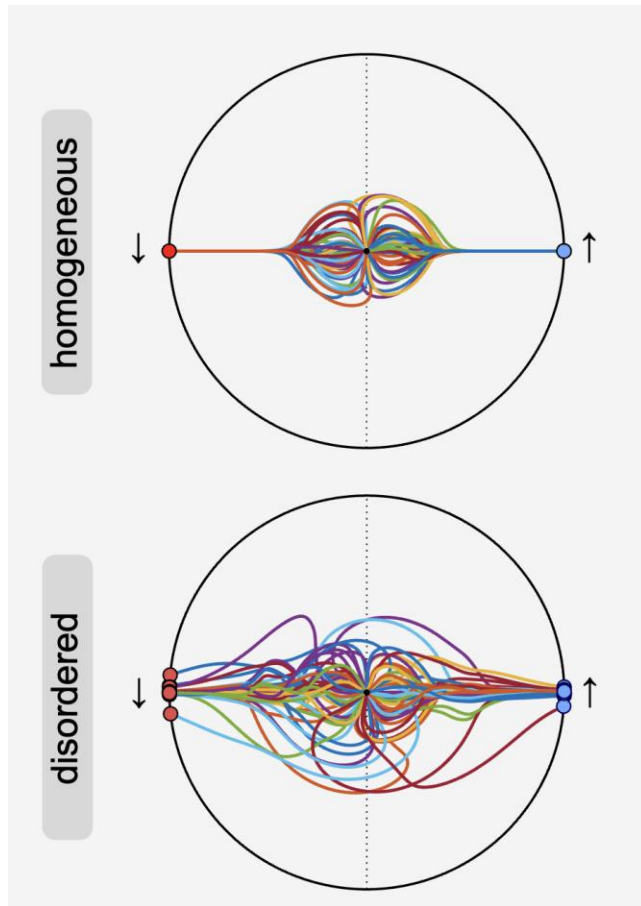
$E(\boldsymbol{\theta}) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} \cos(\theta_i - \theta_j) + \sum_{i=1}^N \mu_i \sin(\theta_i)^2$

Oscillator Ising machine (OIM): $\dot{\theta}_i = \sum_{j=1}^N J_{ij} \sin(\theta_j - \theta_i) - \mu_i \sin(2\theta_i)$

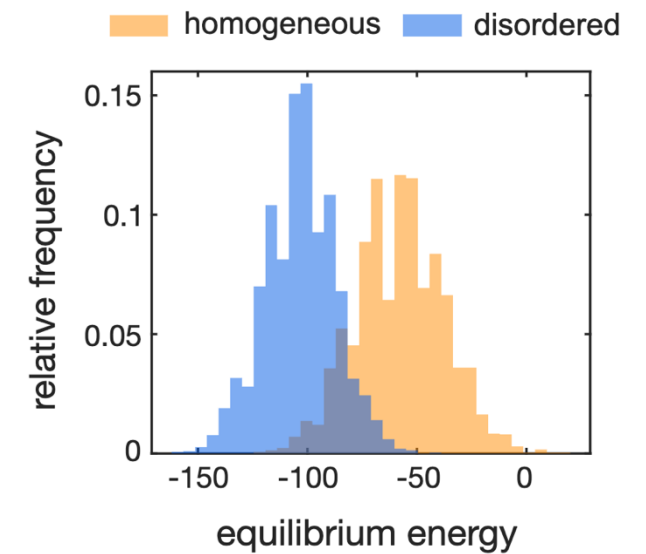
$\mu_i \sim \mathcal{N}(\mu, \sigma^2)$

$\theta_i^*(\mathbf{s}) = \begin{cases} 0, & \text{if } s_i = +1, \\ \pi, & \text{if } s_i = -1, \end{cases}$

Disordered oscillator Ising machines



$$\text{Ising Hamiltonian: } H(s) = -\frac{1}{2} \sum_{i=1}^N \sum_{j=1}^N J_{ij} s_i s_j, \quad s_i \in \{-1, +1\}$$

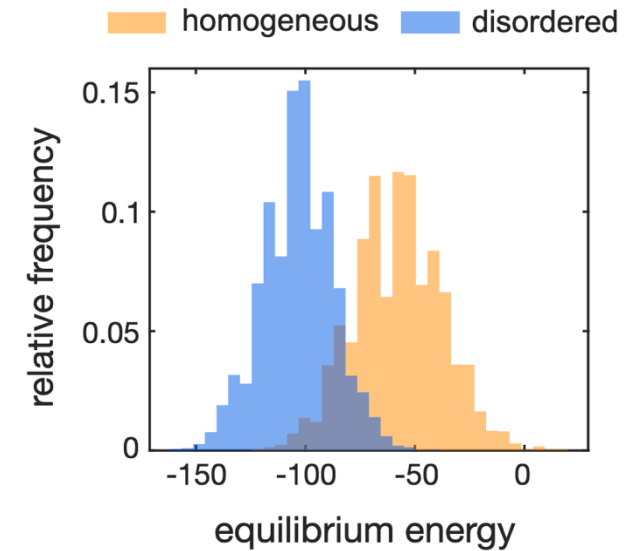
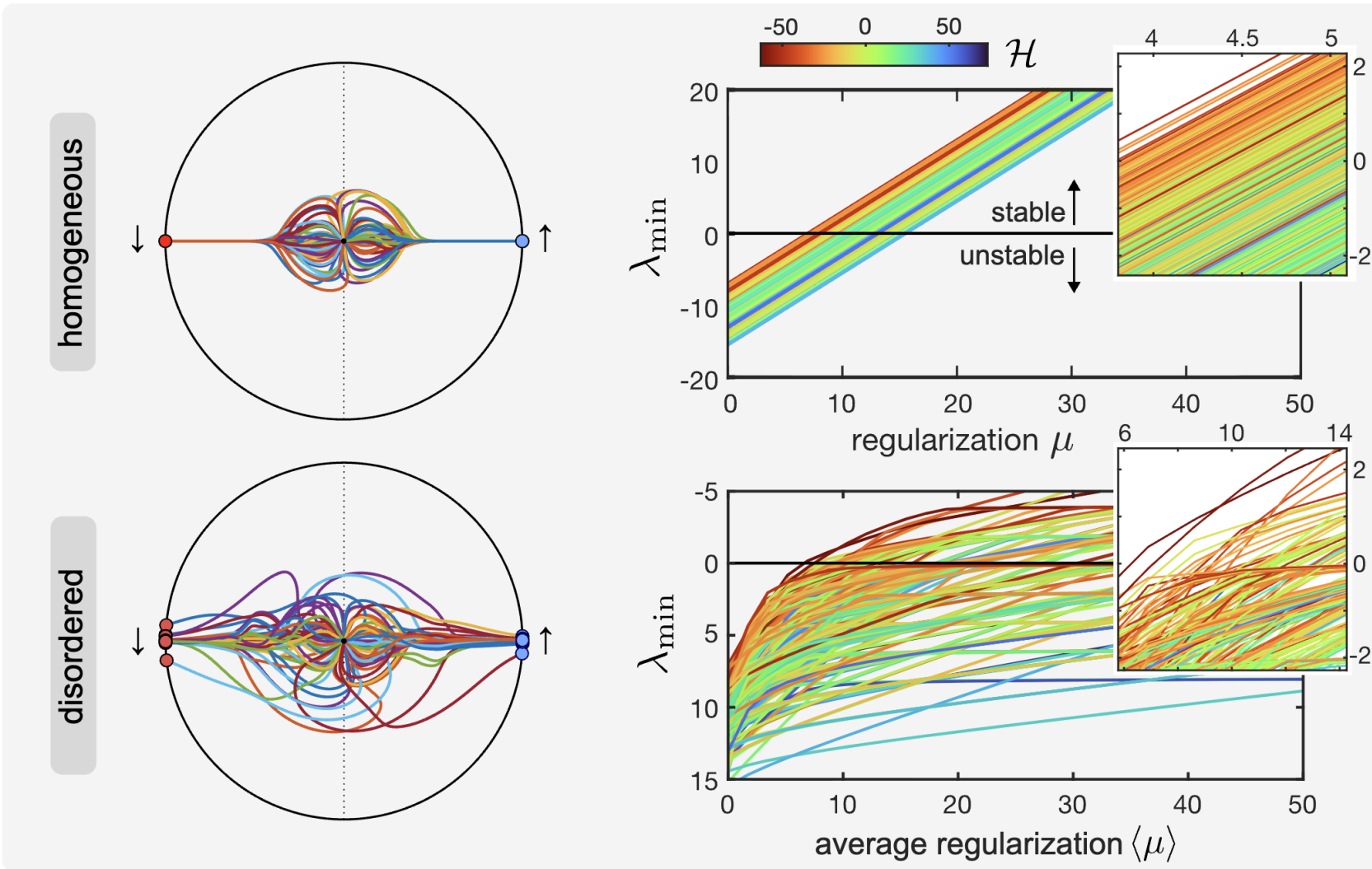


$$\text{Oscillator Ising machine: } \dot{\theta}_i = \sum_{j=1}^N J_{ij} \sin(\theta_j - \theta_i) - \mu_i \sin(2\theta_i)$$

(OIM)

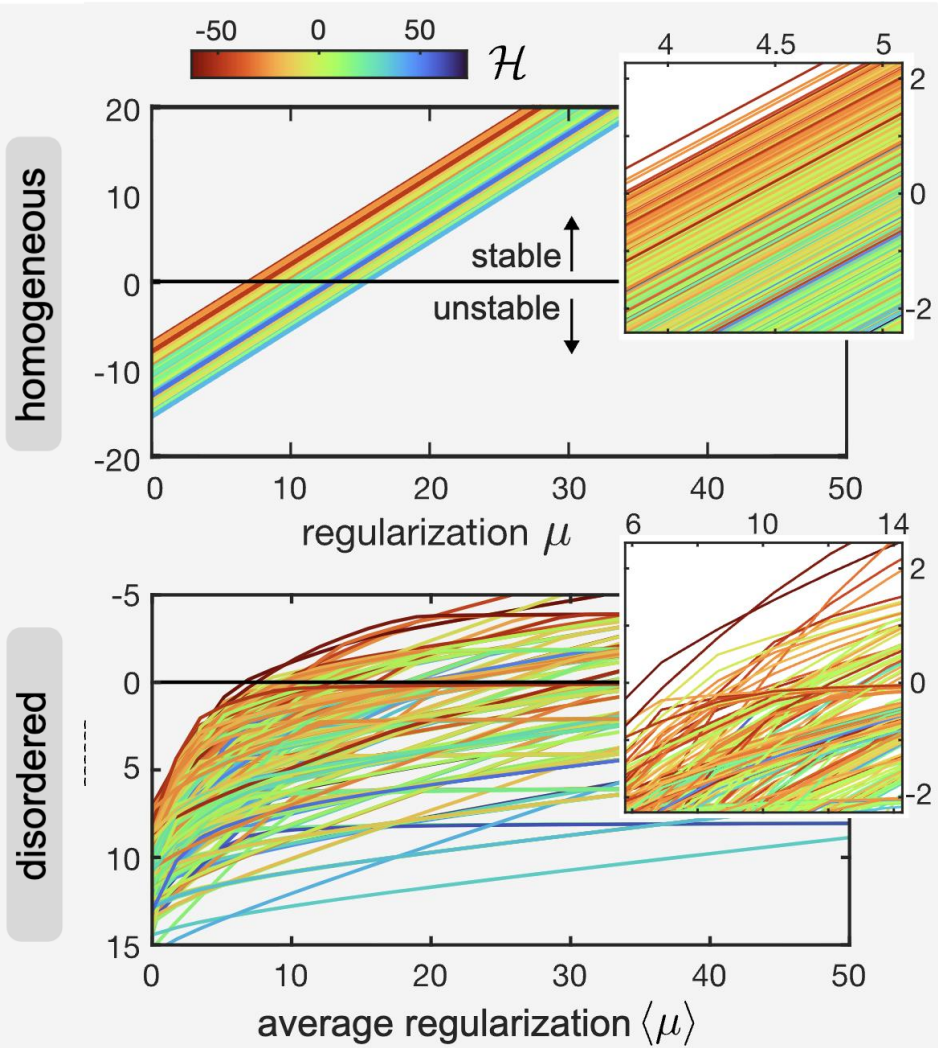
$$\mu_i \sim \mathcal{N}(\mu, \sigma^2)$$

Disordered oscillator Ising machines



Allibhoy, **ANM**, Pasqualetti, Motter.
Proc. IEEE CDC (2025).

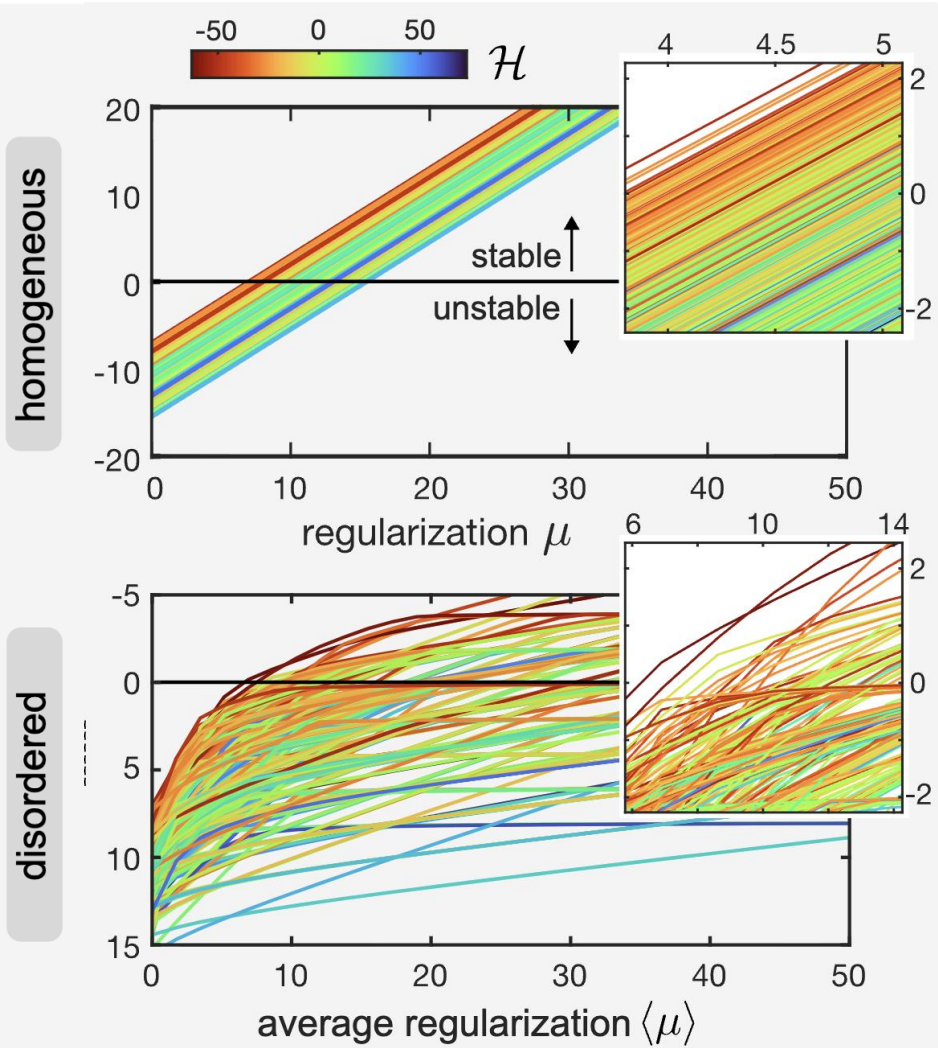
Design principles for biased OIMs



$\mathbb{E}[\lambda_{\min} | H = h] \approx$ Function of:

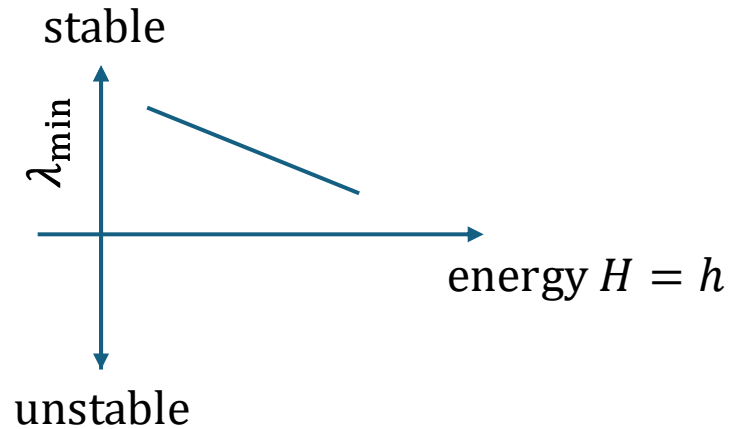
- graph statistical properties (N and p)
- regularization statistical properties ($\mathbb{E}[\mu]$ and $\text{Var}[\mu]$)

Design principles for biased OIMs

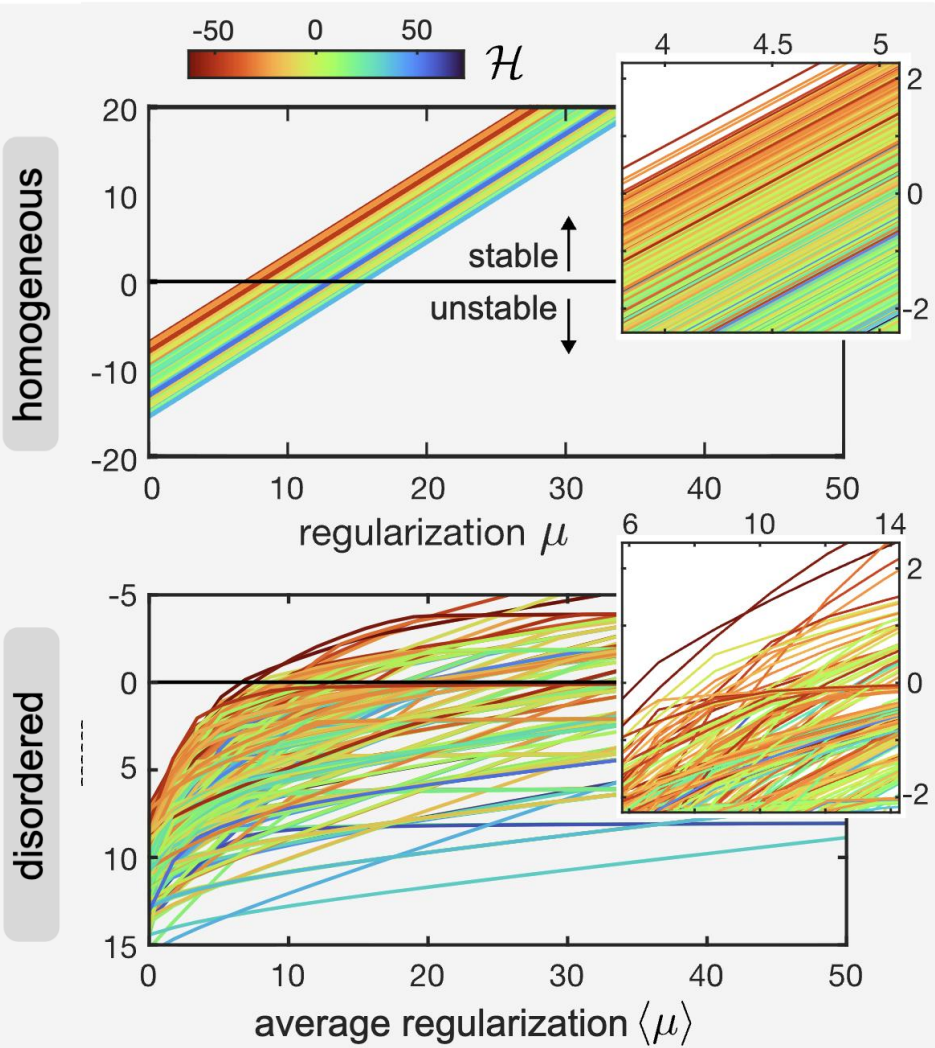


$\mathbb{E}[\lambda_{\min} | H = h] \approx$ Function of:

- graph statistical properties (N and p)
- regularization statistical properties ($\mathbb{E}[\mu]$ and $\text{Var}[\mu]$)

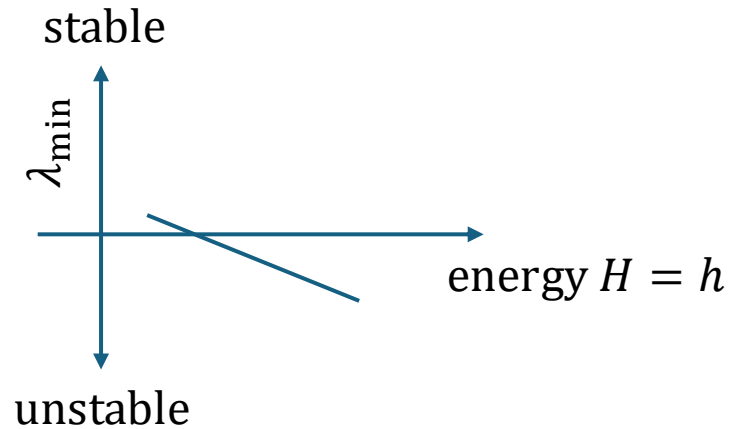


Design principles for biased OIMs

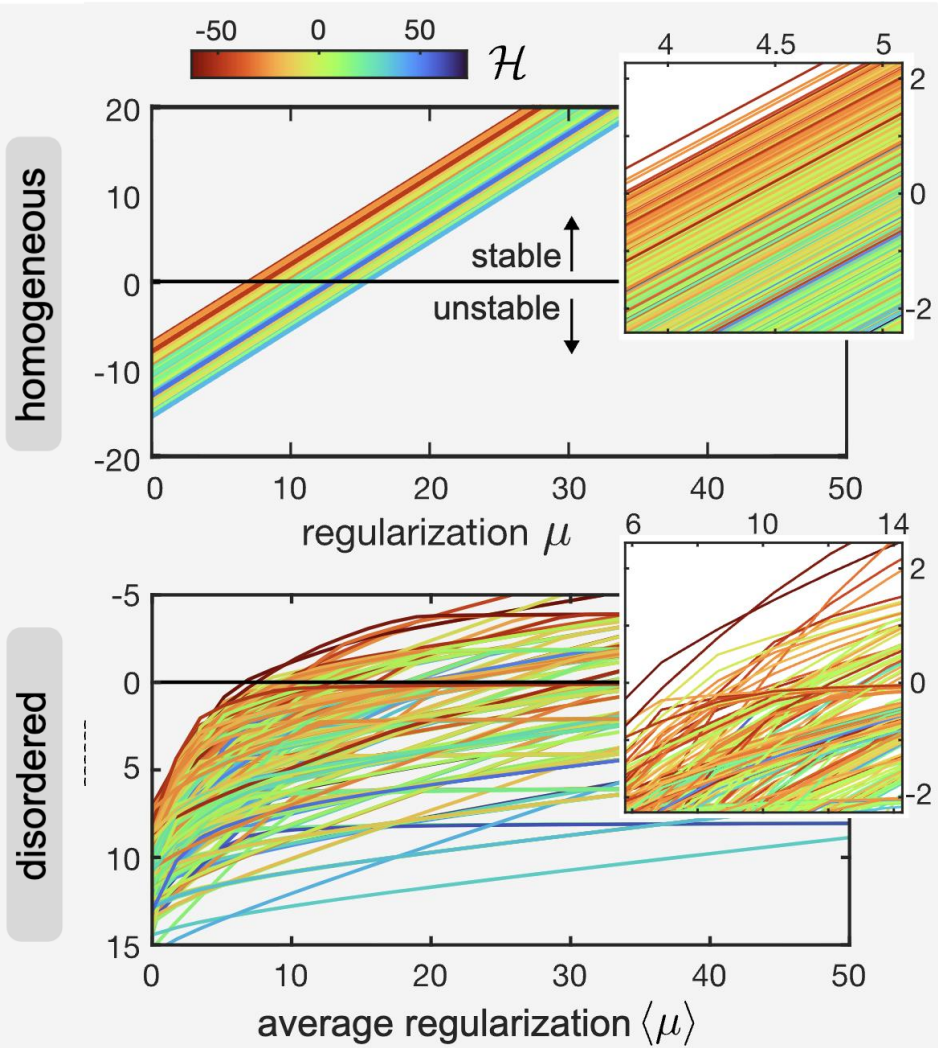


$\mathbb{E}[\lambda_{\min} | H = h] \approx$ Function of:

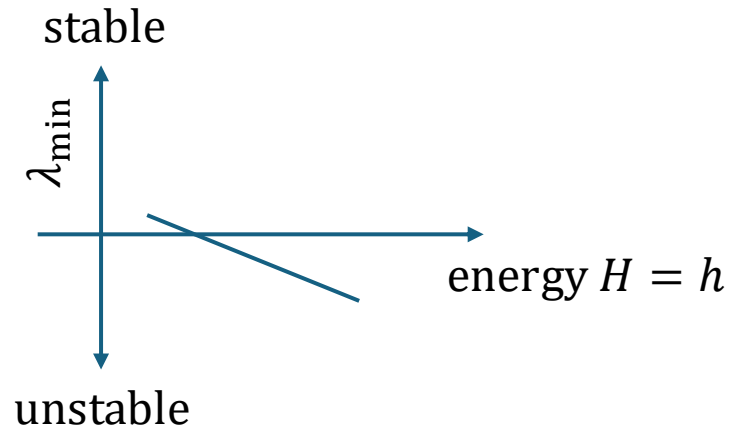
- graph statistical properties (N and p)
- regularization statistical properties ($\mathbb{E}[\mu]$ and $\text{Var}[\mu]$)



Design principles for biased OIMs

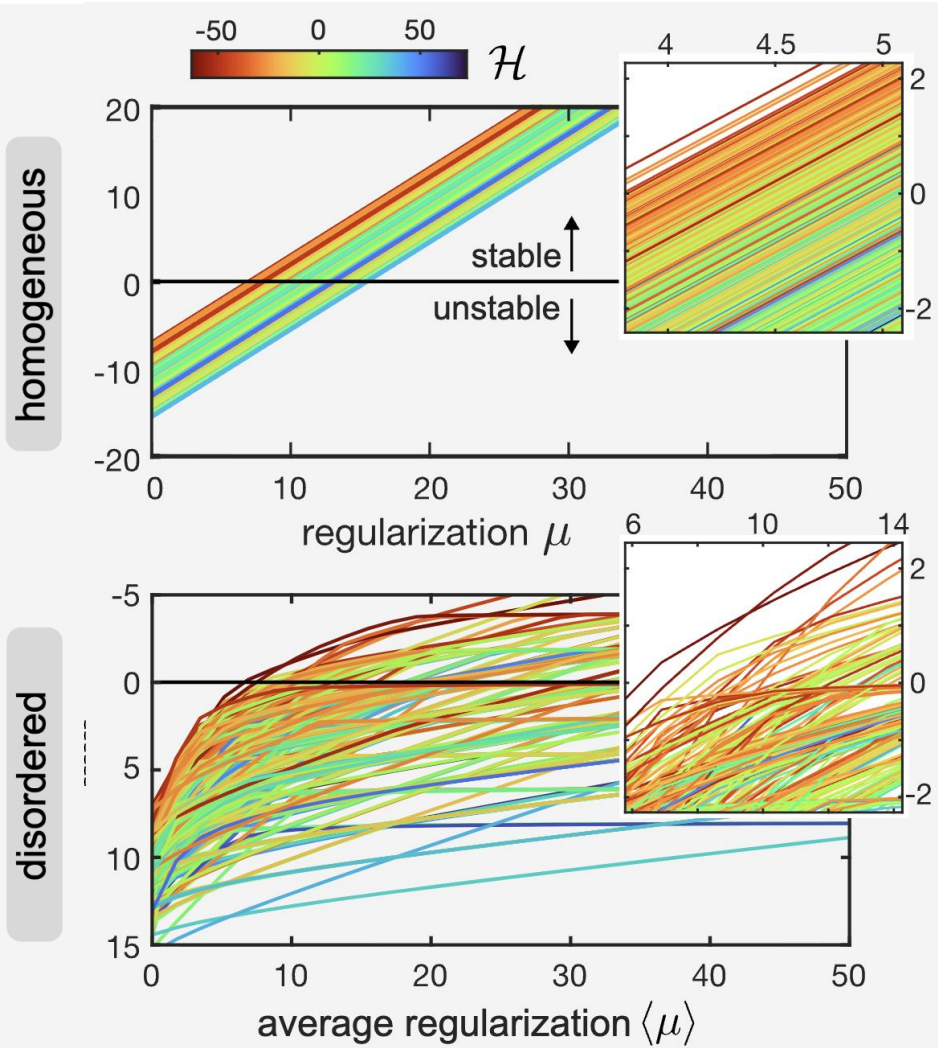


$$\mathbb{E}[\lambda_{\min} | H = h] \approx - \left(\frac{2}{N} + \frac{4 \text{Var}[\boldsymbol{\mu}]}{N(N-1)p} \right) h + 2\mathbb{E}[\boldsymbol{\mu}] - \sqrt{(2(N-1)p + 4 \text{Var}[\boldsymbol{\mu}]) \log N}$$

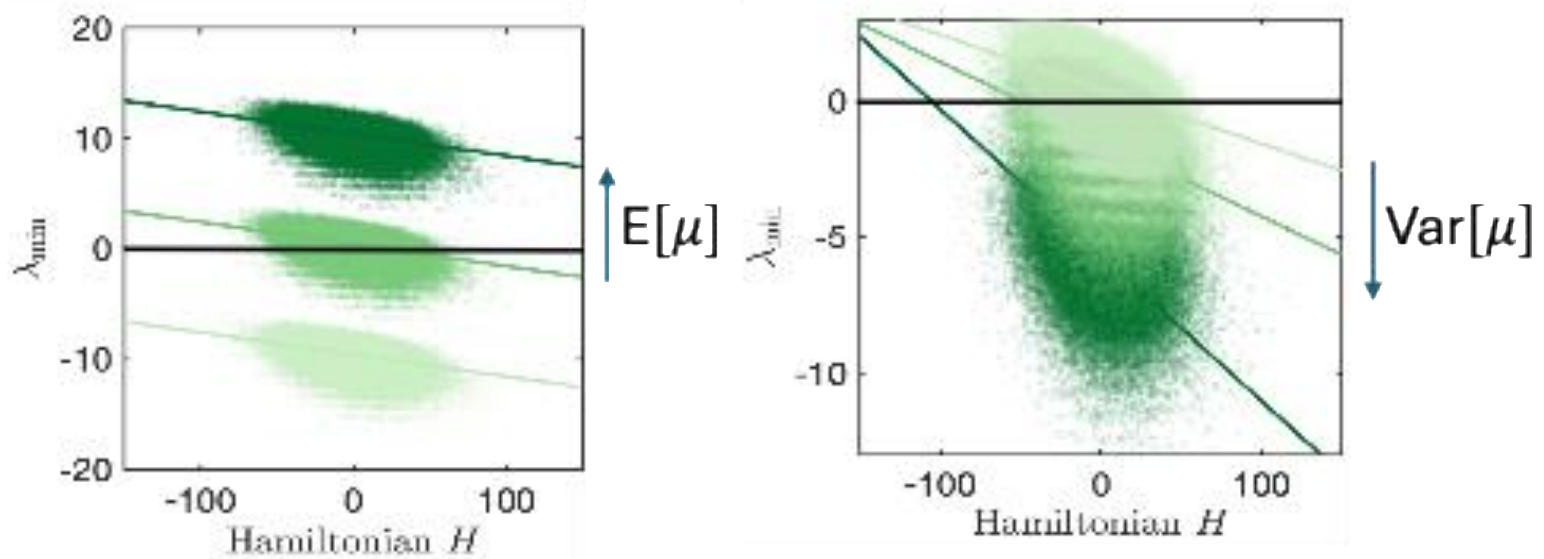


Allibhoy, **ANM**, Pasqualetti, Motter.
Proc. IEEE CDC (2025).

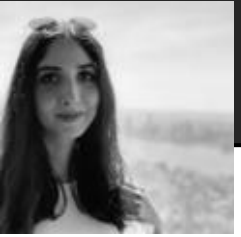
Design principles for biased OIMs



$$\mathbb{E}[\lambda_{\min} | H = h] \approx - \left(\frac{2}{N} + \frac{4 \text{Var}[\mu]}{N(N-1)p} \right) h + 2\mathbb{E}[\mu] - \sqrt{(2(N-1)p + 4 \text{Var}[\mu]) \log N}$$



Ongoing simulations and experiments



Malihe Farasat



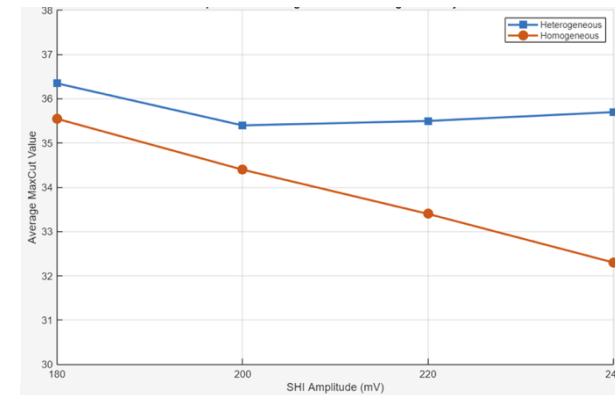
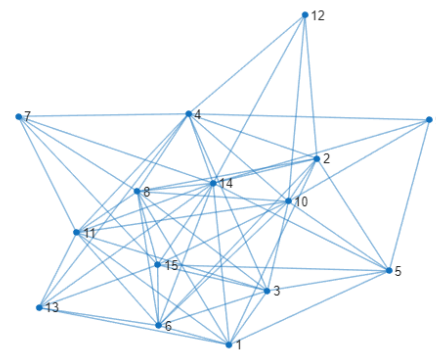
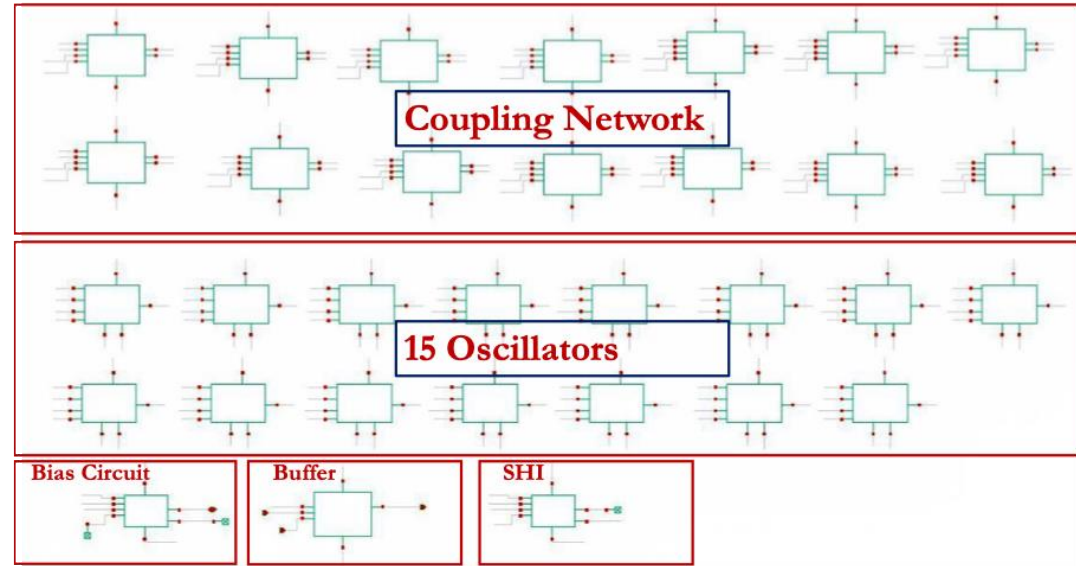
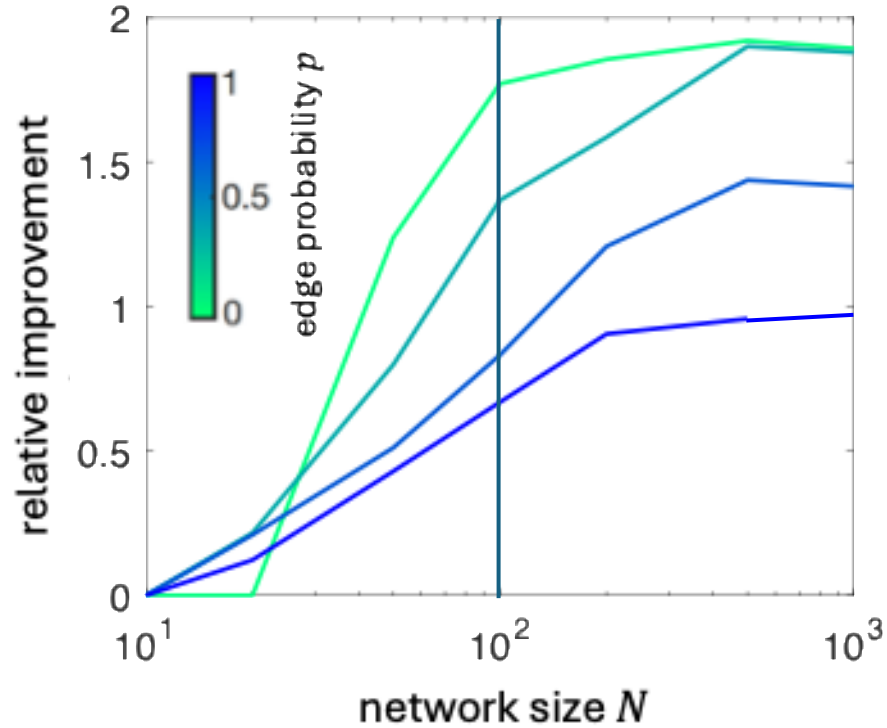
Sajib Bain



Abir Hasan

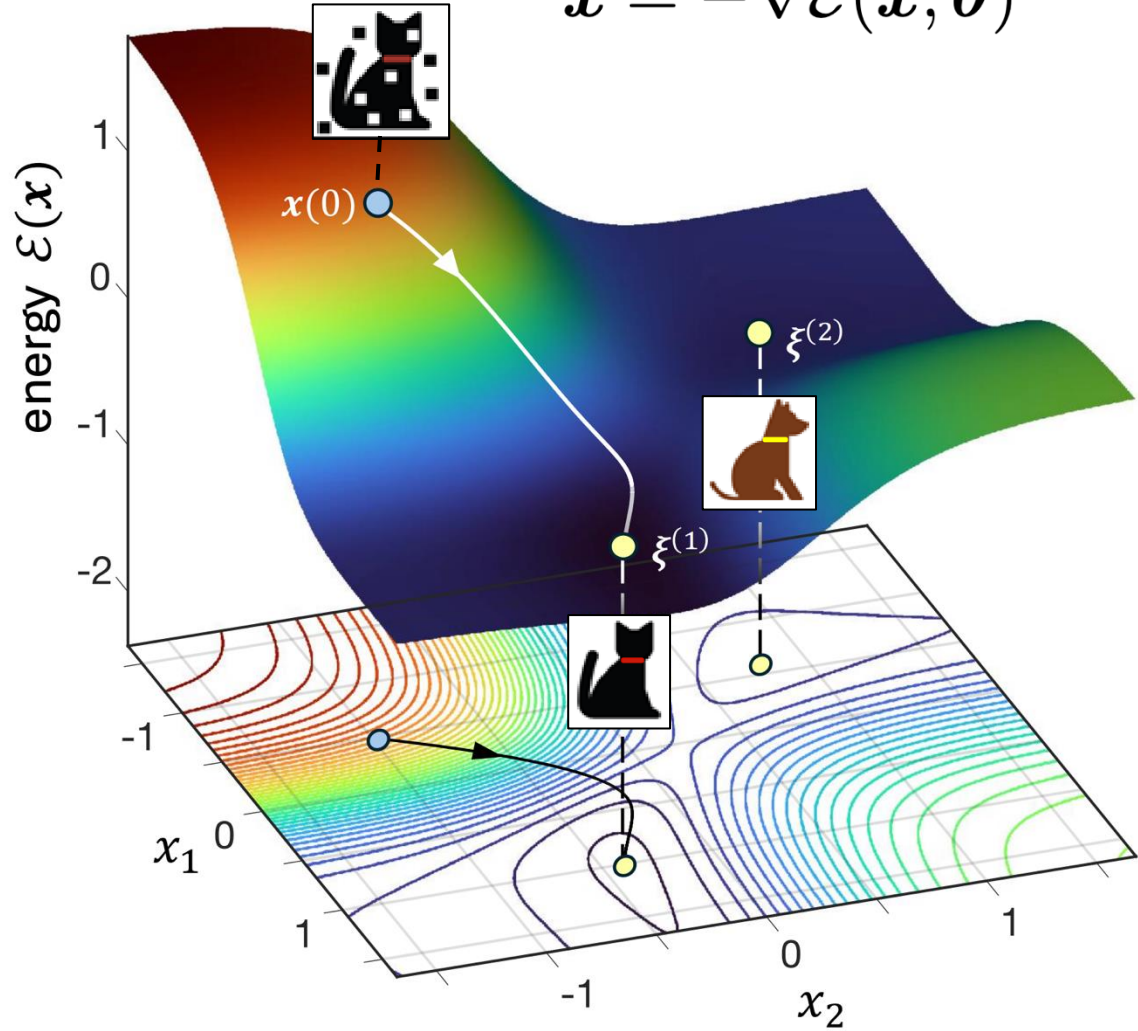


Nikhil Shukla
UVA



Future research direction

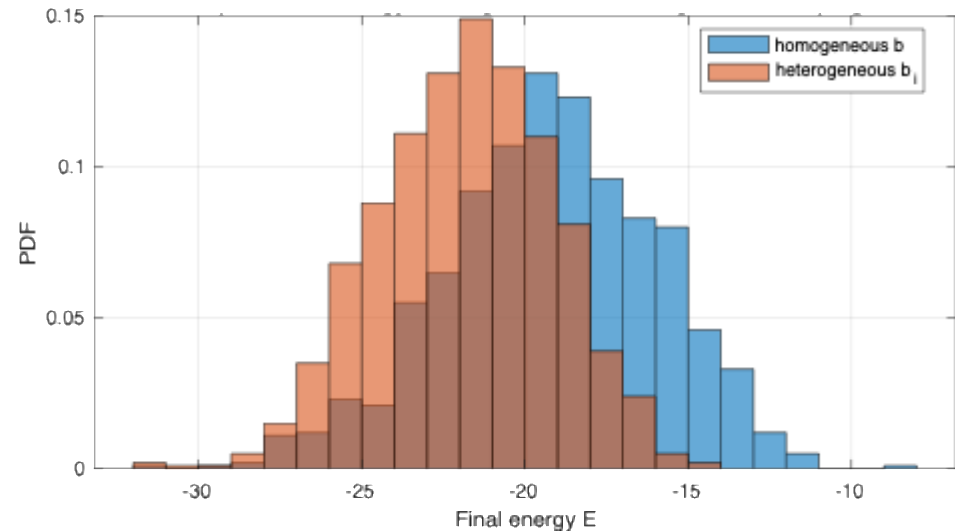
$$\dot{\mathbf{x}} = -\nabla \mathcal{E}(\mathbf{x}; \boldsymbol{\theta})$$



Hopfield network

$$-\dot{\mathbf{x}} = -D\mathbf{x} + W\boldsymbol{\Phi}(\mathbf{x}) + B\mathbf{u}$$

$$D = \begin{bmatrix} d_1 & & & \\ & d_2 & & \\ & & \ddots & \\ & & & d_N \end{bmatrix}$$



Acknowledgments

montanariarthur.com

slides available at my website



Ahmed Allibhoy
UCI



Fabio Pasqualetti
UCI



Nikhil Shukla
UVA



Dmitry Krotov
independent



Francesco Bullo
UCSB



Yiming Wang
NU



Pietro Zanin
NU



Ana Barioni
NU



Adilson Motter
NU



Camila Montanari



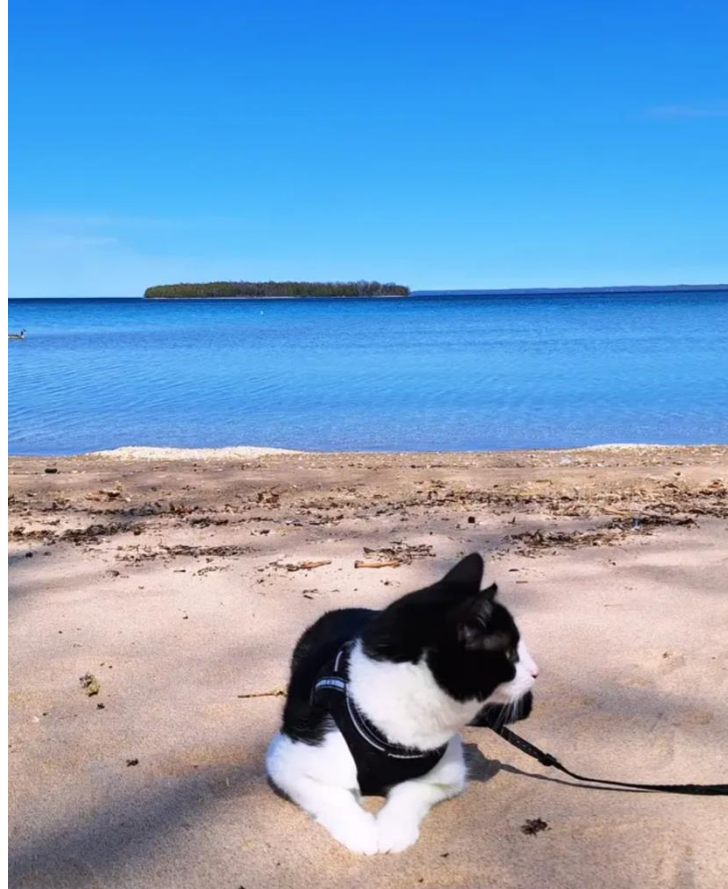
Cats!

montanariarthur.com

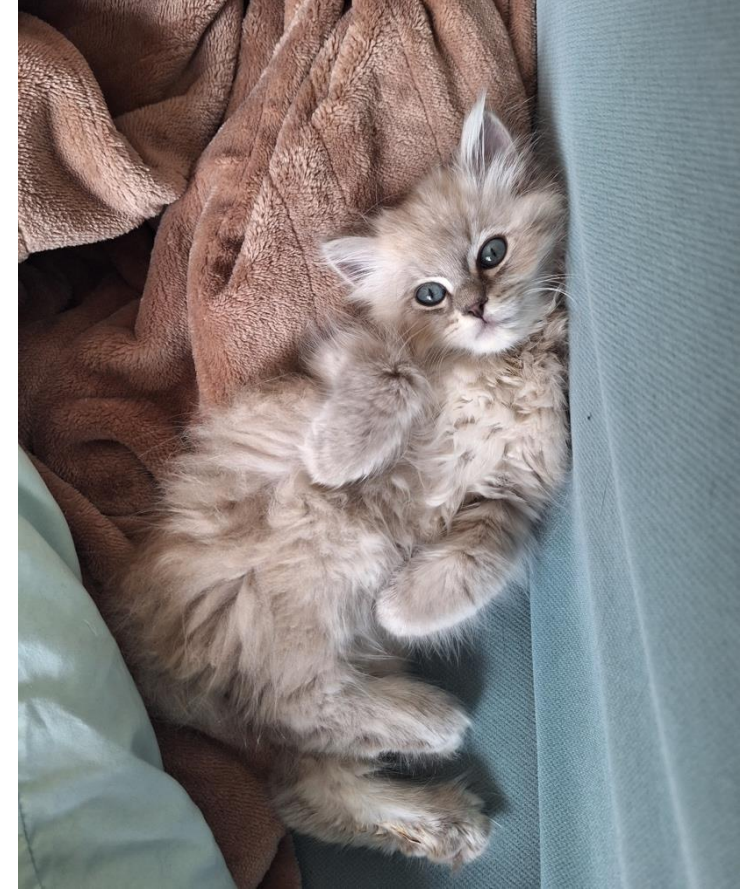
slides available at my website



Pollo



Sushi



Tofu